

## GOES-5 AOD Data Assimilation: Plans for Geostationary Observations

### Patricia Castellanos & Arlindo da Silva

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#### **Comparison of MODIS Standard AOD Retrievals**



- The aerosol data assimilation problem requires a homogenized AOD observing system across different platforms
- Biases between datasets can propagate in the model forecast and lead to artificial time variability.





#### **Empirical Retrievals**

Satellite Sensor Observation [S]

Transfer Function [f] G = f(S, A)

Geophysical Parameter of Interest [*G*]

- f is a continuous function that maps S to G
- Represent *f* with a <u>mathematical function</u> that contains a set of empirical parameters, A
- A are determined from a training dataset of pairs of G and S <u>observations</u>.
  - Training empirically captures physical relationships and tunes away calibration issues.







## **Observations**



#### Satellite Sensor Observation [S]: MODIS MOD04 /MYD04 Level 2 Reflectance

- □ Cloud masked, quality controlled, 10 km data
- Deep Blue Land
  - □ 3 channels over bright surfaces
  - □ 412 nm, 470 nm, and 670 nm

Dark Target Land

- 9 channels over dark surfaces
- 412-2100 nm

Geophysical Parameter of Interest [*G*]: 470, 550, 670, 870 nm AOD

- Aerosol Robotic Network (AERONET) observations of AOD
  - □ Global network of sunphotometers
  - 15 minute sampling
  - Low uncertainty (±0.01)





- □ 7 channels over ocean
- □ 470-2100 nm







#### **MODIS-AERONET** Data Pairs



- 15 years of data (2000-2015)
- ~150K Deep Blue data pairs
- ~100K DT-Land data pairs
- ~40K DT-Ocean data pairs

#### Additional Data Screening

- Outlier removal
- □ Cloud Fraction < 0.7
- Used MERRA-2 to "balance" the dataset by aerosol type
  - Dust
  - Smoke (Black Carbon + Organic Carbon)
  - Sea Salt
  - Sulfate

Reduces number of data pairs by half

Petrenko, et al. AMT (2012)





#### **Mathematical Function: Neural Network**

 $\sigma(\boldsymbol{w},\boldsymbol{x}) = \frac{1}{1 + \exp\left(-\boldsymbol{w}\cdot\boldsymbol{x} - \boldsymbol{c}\right)}$ 

1 2

- A set of nodes connected by numerical weights.
- The weights are tuned based on a specific training dataset containing input-output data pairs.
- The superposition of many nonlinear transfer functions (nodes) allow NN's to approximate extremely nonlinear functions

Output





Input<sub>1</sub>

Input<sub>2</sub>

Input<sub>3</sub>

Weight<sub>1</sub>

Weight<sub>2</sub>

Weight<sub>3</sub>

Feed-forward Neural Network

#### **GEOS-5 NNR for AOD**





GMAC



### NNR Training, Testing, Validation

#### Train & Test

- Iteratively train and test adjusting input variables, architecture, etc. to optimize neural network
- Cross Validation
  - K-folding: create K subsets of data, using K-1 for training, and 1 for testing. Iterate K times.

#### Validate

- Use a separate dataset, not used to train/test
- Observations after 2015





9



#### **NNR Training & Testing**





#### **NNR Testing**









#### **NNR Testing at Some Individual Sites**





#### **NNR Validation (Observations after 2015)**







#### From LEO to GEO: Calibration Transfer

- NRT SatCORPS cloud cleared GOES-16 and AHI-8 TOA reflectances
  - Provided by NASA Langley SatCORPS Group (R. Palikonda, W. Smith)
  - 1 full disk scan per hour
- Use MODIS-NNR AOD as targets for training GEO Reflectance observations

**INPUTS** 



#### ► TARGETS

MODIS Aqua NNR AOD 2018-03-11 20Z







#### Preliminary Test with Ocean Data

- Trained NNR with 2-months of MODIS/GOES-16 collocated observations
- ~100K data points
- Currently only 640, 860, and 1600 nm channels provided
- □ No water vapor correction

# **Current Aerosol Analysis: Splitting**



#### 2D AOD ANALYSIS

- Observable 550 nm AOD is 2D
  - MODIS Aqua/Terra: Ocean, Land, Deep Blue channels
  - Constrains column averaged optics
  - Cannot constrain speciation or vertical distribution
- Analysis in observation space:

 $\tau^{a} \equiv Hq^{a} = H\left(q^{b} + \delta q^{a}\right)$  $= \tau^{b} + \delta \tau^{a}$ 

#### GOING TO 3D CONCENTRATIONS

- Based on error covariances:
  - $\delta q^a = BH^T \left( HBH^T \right)^{-1} \delta \tau^a$
- Using ensemble perturbations,  $\delta q^{a} = XY^{T} \left(YY^{T}\right)^{-1} \delta \tau^{a}$
- NRT GEOS-5 uses Local Displacement Ensembles (LDE), in 1D
- Developing EnKF for Aerosols



## In Development: Aerosol EnKF



- As part of GMAO's hybrid system, aerosol ensemble members are produced as a matter of routine
- The same Whitaker-Hamill EnKF used <sup>60</sup> the hybrid Meteorological assimilation <sup>30</sup> has been adapted for aerosols
- Target observation systems
  - Multi-spectral AOD: 470, 550 and 870 nm
  - Lidar attenuated backscatter
  - Sensors: MODIS, VIIRS, GEO, CATS/CALIOP, TropOMI



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#### **Summary & Outlook**

- The NNR provides a way to homogenize the AOD observing system for data assimilation
- A NNR for GOES-16 and AHI-8 will be developed using the MODIS-NNR AOD data as targets
  - Demonstrates the need for continuity in the observing system
- Innovate the training methodology
  - Multi-channel AOD training allows for physical constraints on cost function
  - Use p.d.f. type of targets spread in the solution indicates the uncertainty in the NNR AOD.

