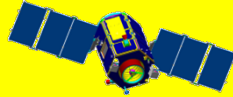




KOMPSAT-1



KOMPSAT-2



KOMPSAT-3



KOMPSAT-5



KOMPSAT-3A



Korea Aerospace Research Institute

115 Gwahangro, Yuseong-gu Daejeon, 305-333, Korea

Calibration and Validation, and Image data Quality for KOMPSAT-3

September 30, 2014

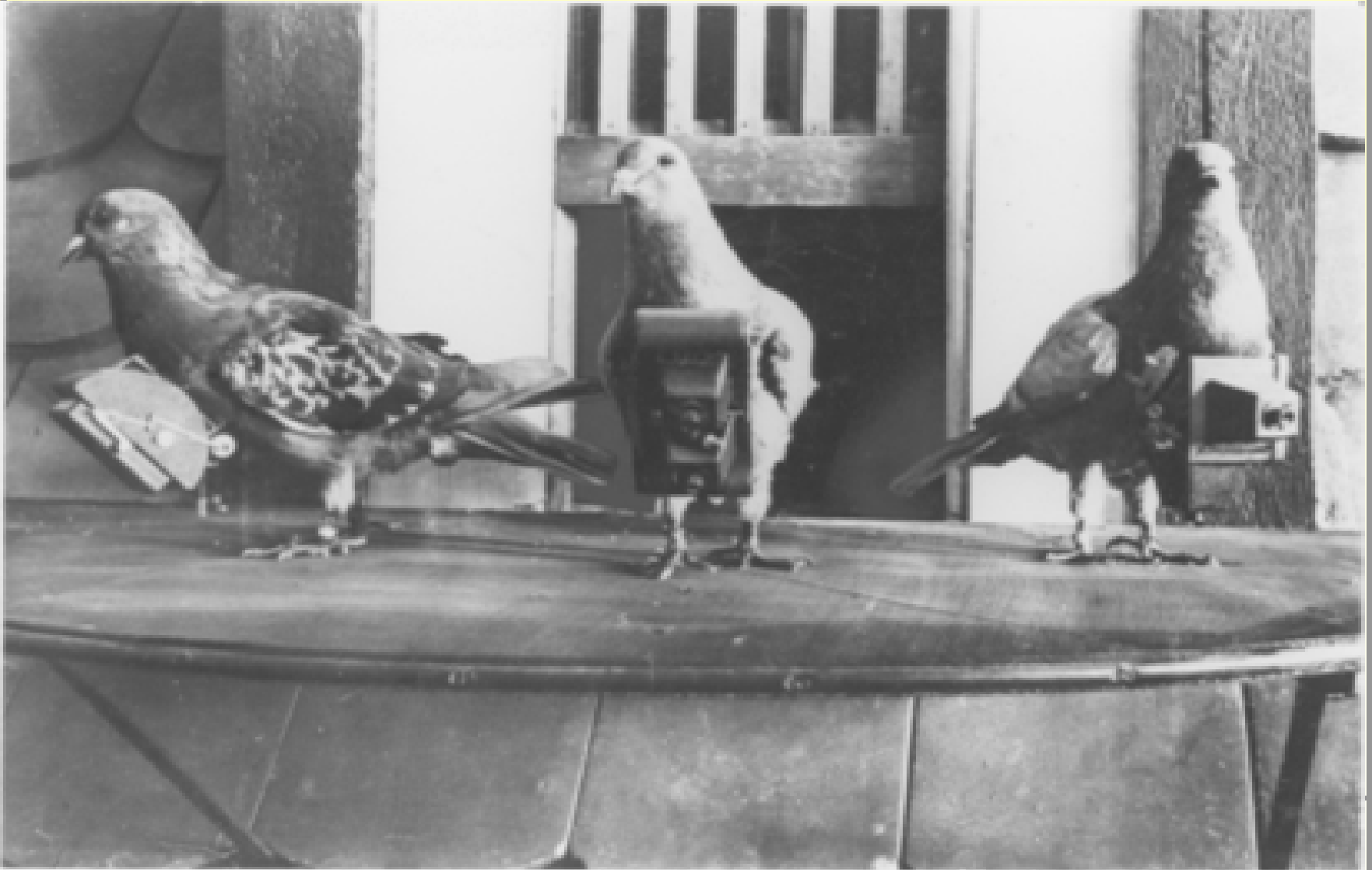
DongHan Lee^{a,b}, DooChun Seo^a, HeeSeob Kim^a

EungSik Lee^a, MinA Kim^a, HaeJin Choi^a

^a Korea Aerospace Research Institute (KARI)

^b USGS EROS Visiting Scientist

Mom~! & Dad~! of Artificial Remote Sensing Satellite



Agenda

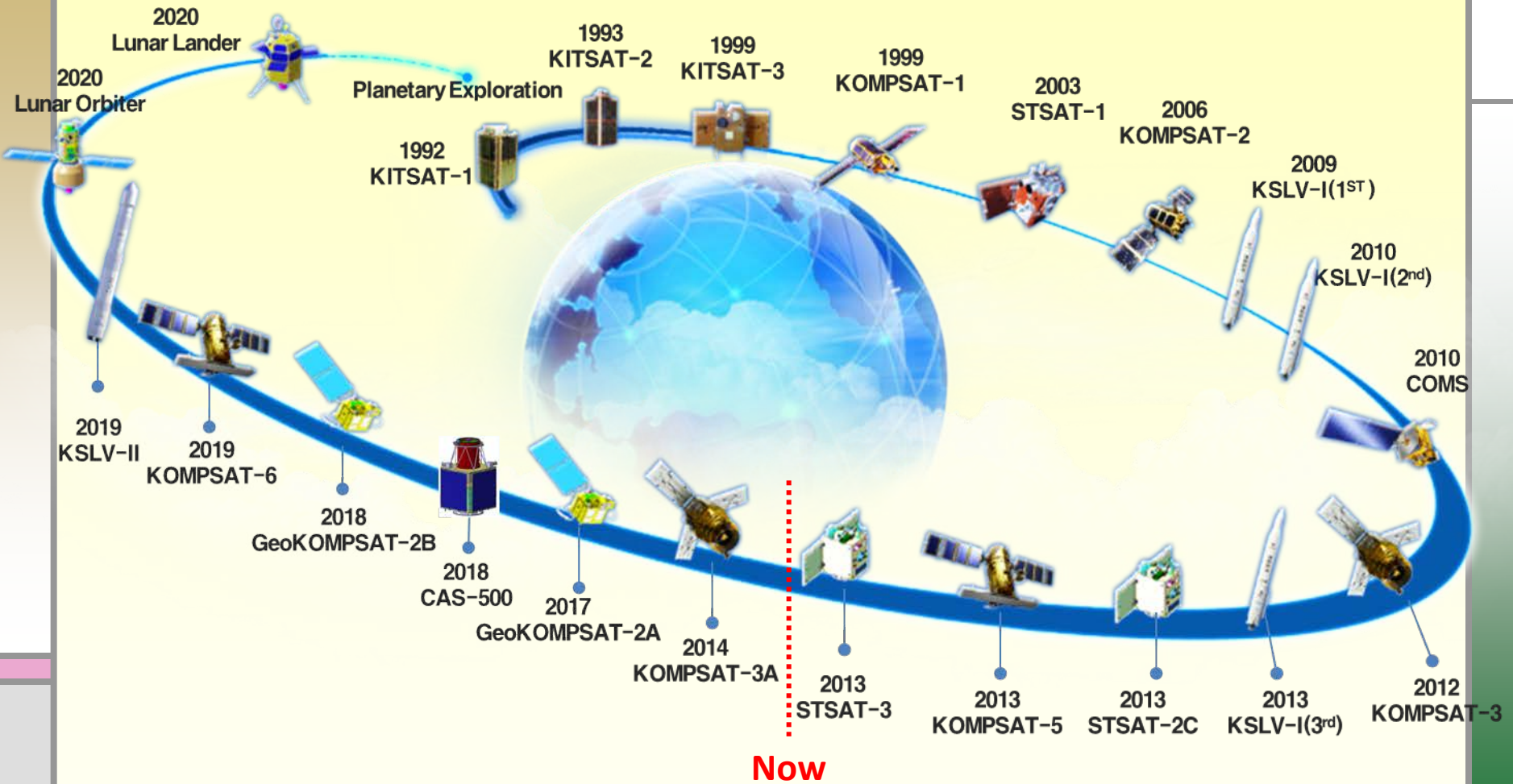
KOMPSAT-3 Calibration and Validation

KOMPSAT-3 Image data Quality


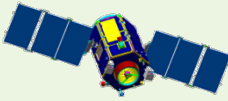


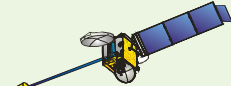

KOMPSAT Program in KARI

KOMPSAT-3 Cal/Val

Space Program in Korea



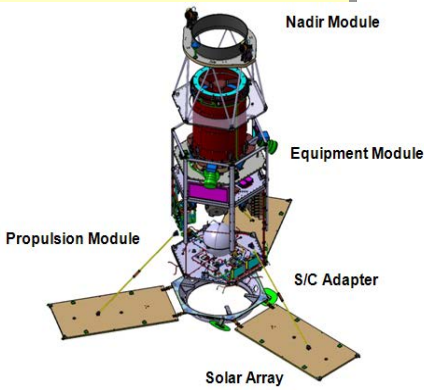
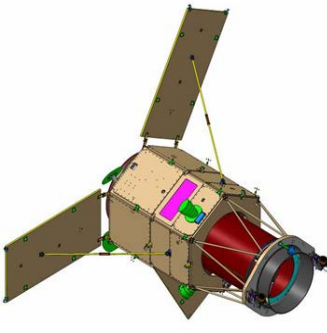
KOMPSAT Program in KARI

	KOMPSAT-1	KOMPSAT-2	KOMPSAT-3	KOMPSAT-5	COMS	KOMPSAT-3A
						
Payload	EOC, OSMI	MSC	AEISS	COSI	MI, GOCI	KISS
	Visual	Visual	Visual	SAR-X	Meteorology	Visual+MWIR
Launch	1999~2008	2006~	2012.5~	2013.7~	2010~	2014.00
Performance	6.6m (EOC) 1km (OSMI)	1m, 4m 10bit	0.7m, 2.4m 14bit	1m, 3m X-band	500m	0.55m, 2.2m 5.5m (MWIR)
Image mode	Strip	Strip	Spot, Strip, Wide	HR, Strip, Wide		Spot, Strip, Wide
Swath	15km	15km	15km	15km	2,500km	15km
Orbit	Sun-Sync	Sun-Sync	Sun-Sync	Sun-Sync	Geo-Station	Sun-Sync

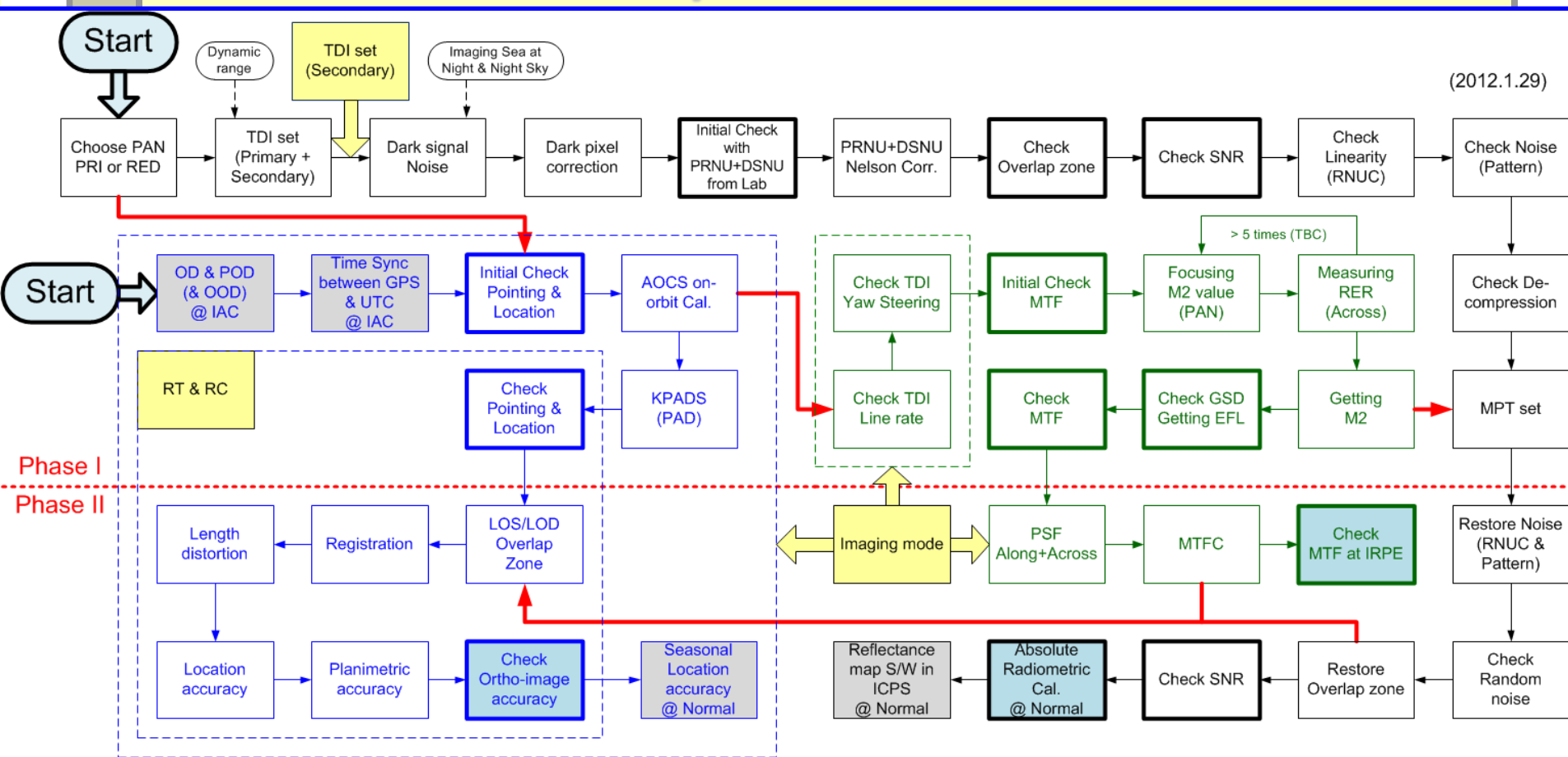
KOMPSAT-6 (SAR) & COMS-2 will be developed by KARI after KOMPSAT-5 & COMS

KOMPSAT-3 Overview

Ground Sampling Distance	(PAN) 0.7 m @altitude 685km(nadir) (MS) 2.8 m @altitude 685km(nadir)
Swath Width	16 km (nadir)
Spectral Bands	PAN : 450 ~ 900 nm
	MS1 (Blue) : 450 ~ 520 nm
	MS2 (Green) : 520 ~ 600 nm
	MS3 (Red) : 630 ~ 690 nm
	MS4 (NIR) : 760 ~ 900 nm
Dynamic Range	14 bits / pixel
Modulation Transfer Function	(PAN) 8%, (MS) 12%
Signal to Noise	> 100
Location Accuracy	< 70 m CE90 (< 30 m RMSE is expected)
Orbit	Sun Synchronous Orbit
	<ul style="list-style-type: none"> Altitude : 685.13 ± 1km Inclination : 98.14 ± 0.05 degree MLTAN : 13:30 +10/-15 min



KOMPSAT-3 Cal/Val work Flow in LEOP



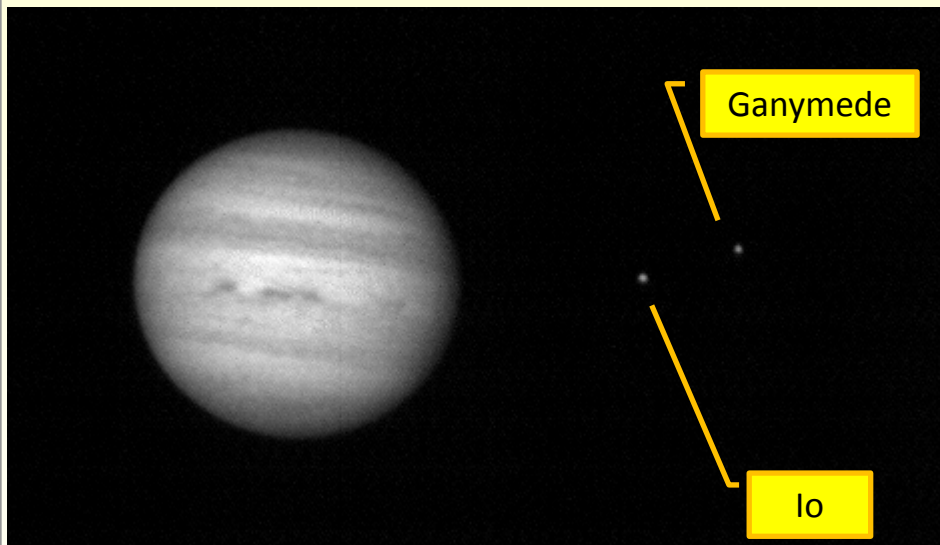
Performance of KOMPSAT-3 after Cal/Val

	Key Item	Requirement Value	Validated Value	Condition
Cal/Val Phase I	SNR	100	>> 100 (TDI 64)	
	MTF	8%(PAN) 12%(MS)	Across: 8~10% (TDI 64) Along: 6~8% (TDI 64) > 19% (MS)	Strip imaging Level 0
	GSD	0.7m(PAN) 2.8m(MS)	0.7m (PAN)	Strip & Nadir imaging
	Pointing accuracy	1.2km	Across: 90m Along: 1 sec	Strip imaging
	Location accuracy	70m CE90	< 70m CE90	With POD & PAD Strip imaging
Cal/Val Phase II	MTF after MTFC	13%(PAN) 19%(MS)	> 20% (PAN)	Level 0
	Registration	0.5pixel RMS (MS)	0.5pixel RMS (MS)	Strip imaging
	Ortho-image accuracy	3.5m CE90 (Horizontal)	3.5m CE90 (Horizontal)	Strip imaging

Radiometric Cal/Val for KOMPSAT-3

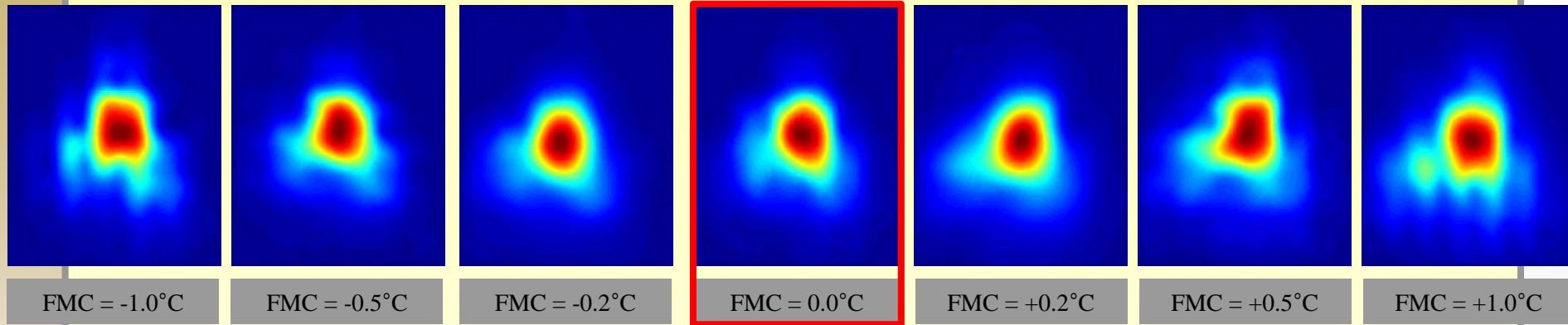
Geometric Cal/Val for KOMPSAT-3

Spatial Cal/Val for KOMPSAT-3



Jupiter~!
2012.07.18, PAN_3

Focusing with Star image data



FMC Temperature(°C)		FWHM - Across			FWHM-Along			MTF(%)	
at Star	at Ground	20%	50%	80%	20%	50%	80%	Across	Along
-1.46	-1.00	2.881	1.666	0.997	2.816	1.803	1.115	12.52	7.85
-0.96	-0.50	2.750	1.665	0.957	2.644	1.745	1.082	11.41	9.13
-0.67	-0.21	2.834	1.580	0.926	2.765	1.789	1.065	13.22	7.37
-0.46	0.00	2.907	1.650	1.000	2.458	1.587	0.901	12.44	12.69
-0.26	0.20	2.612	1.650	0.997	2.994	1.813	1.072	12.14	8.02
0.04	0.50	3.207	1.747	1.011	2.896	1.808	1.124	10.54	7.67
0.54	1.00	3.122	1.773	1.065	2.929	1.801	1.019	10.76	7.82

Concept of MTF Compensation (MTFC)

- **Purpose and Necessity of MTF Compensation**

- Restoration of the distortion of the image data from the Sensor deviation.
- Enhancement of the sharpness of the image data
- But, increase the Noise and get the other distortion; Ringing, etc.

- **Highlight the only information in Image data**

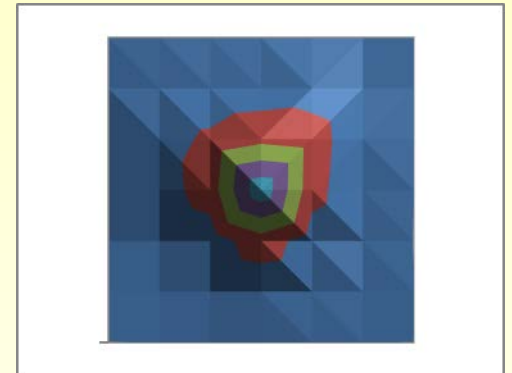
- But, must not distort the information.
- Change, Remove, Add (X)

- **Suppress the Noise against MTFC**

- Match the MTFC with the De-noising filter
- Don't read any information as the Noise.
- Don't read any noise as the Information.

- **MTFC algorithm must have the specific character of the Sensor.**

- PSF (Point Spread Function) has to be measured by the optimum method (Star).
- Optimal MTFC algorithm ([Wiener filter](#), Lucy Richardson, Sparse Prior, etc.)

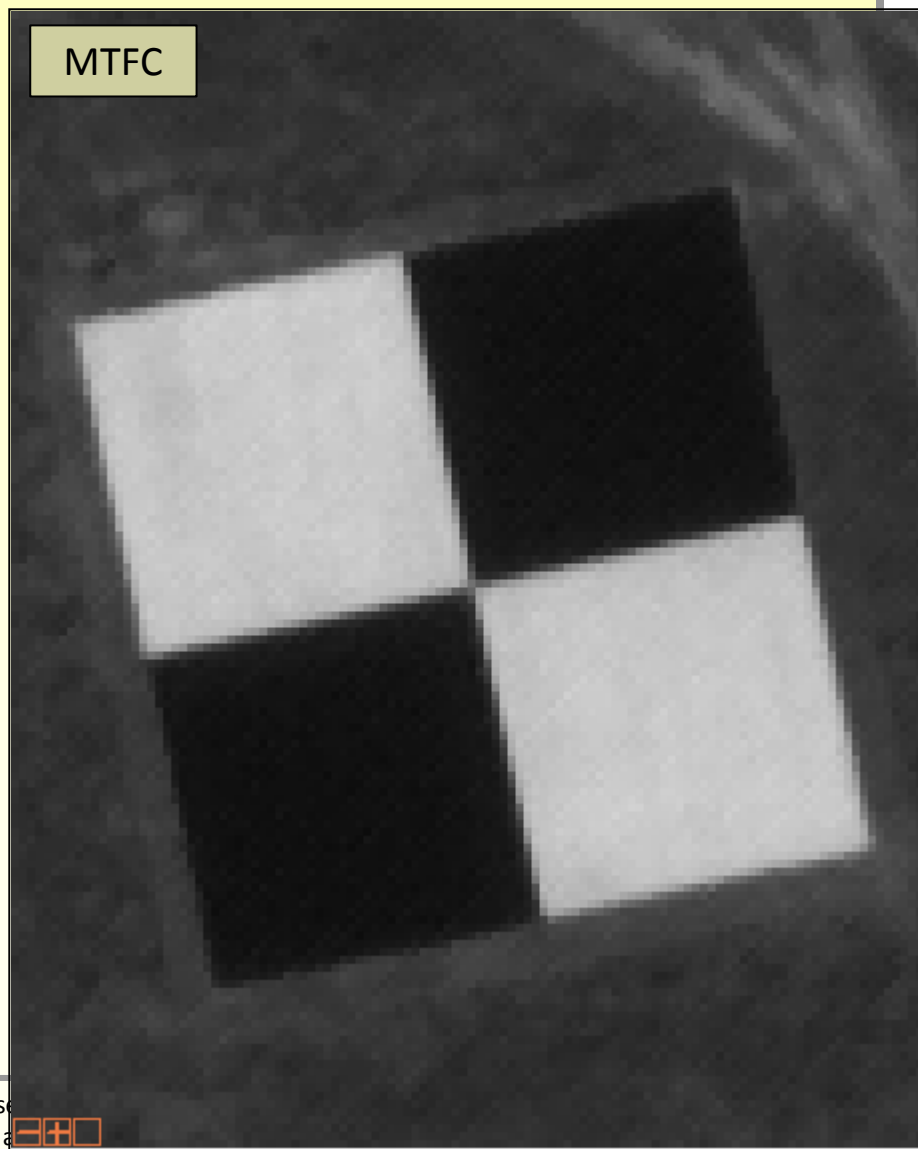
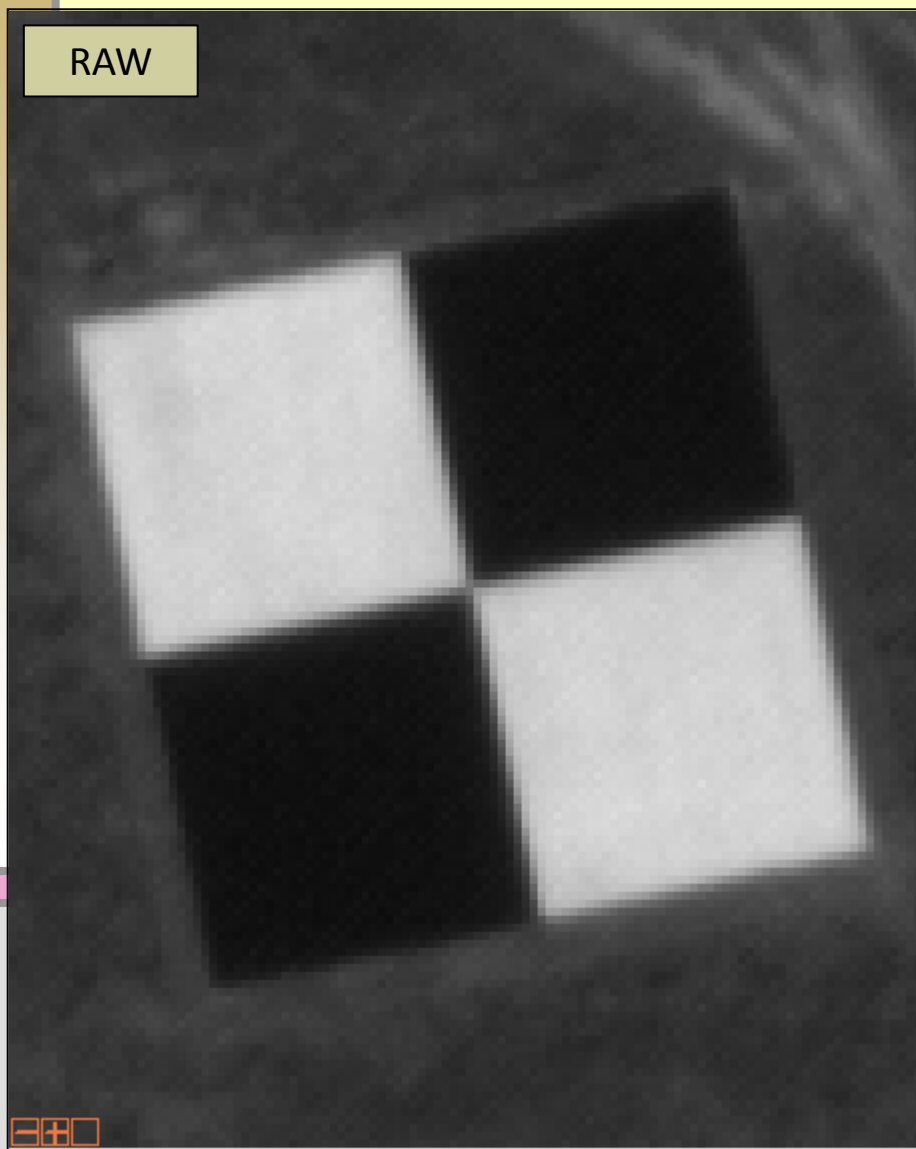


KOMPSAT-3 PSF
from Star

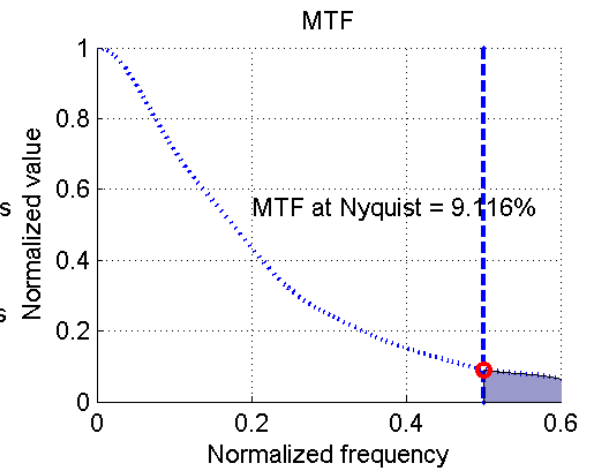
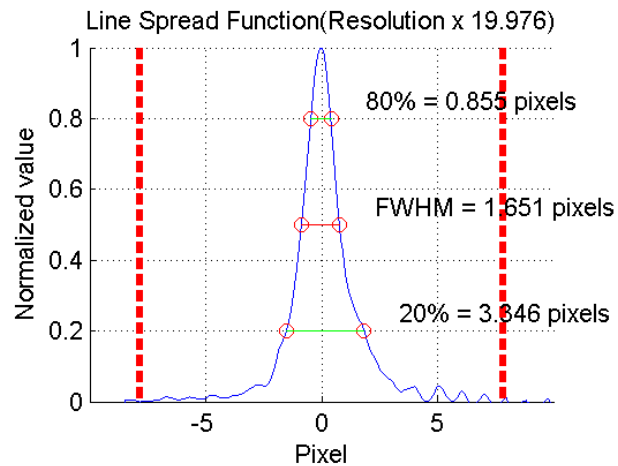
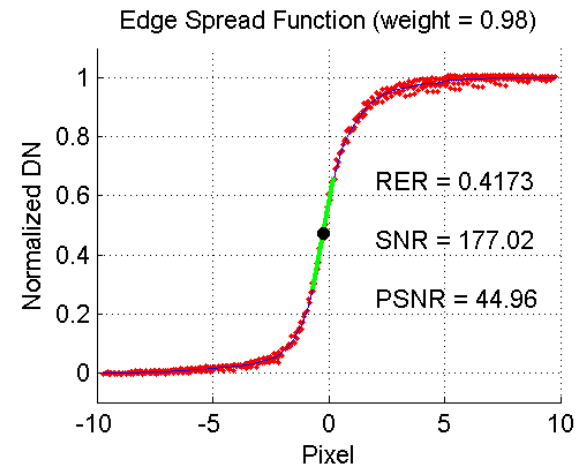
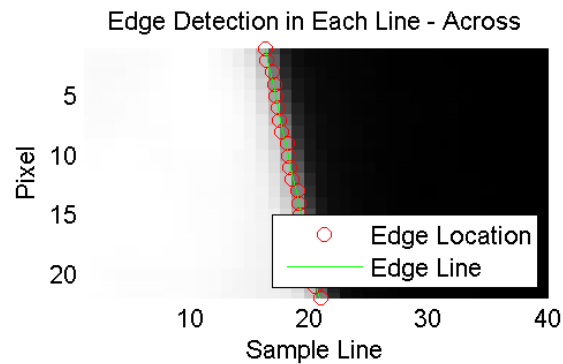
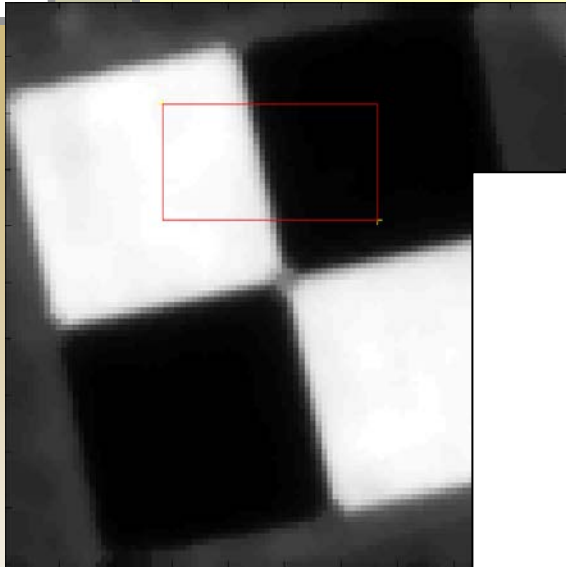
MTFC of KOMPSAT-3 (I like it~!)

RAW

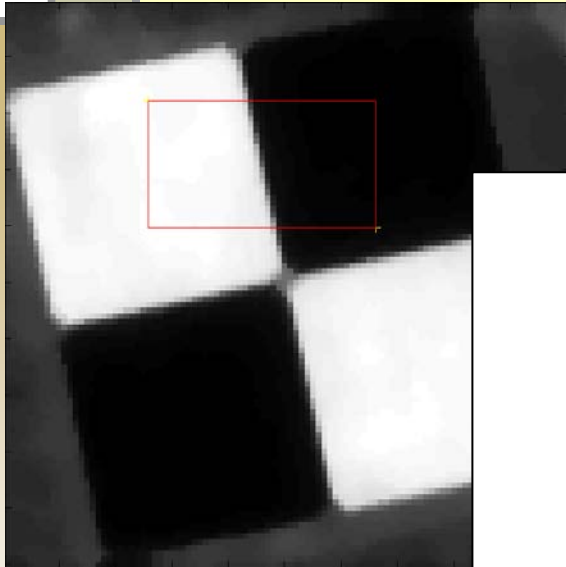
MTFC



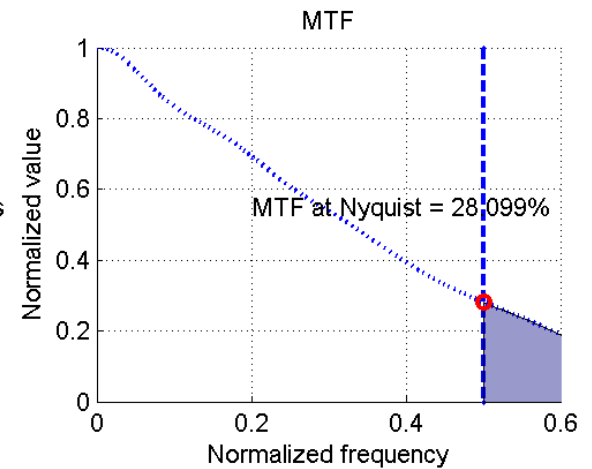
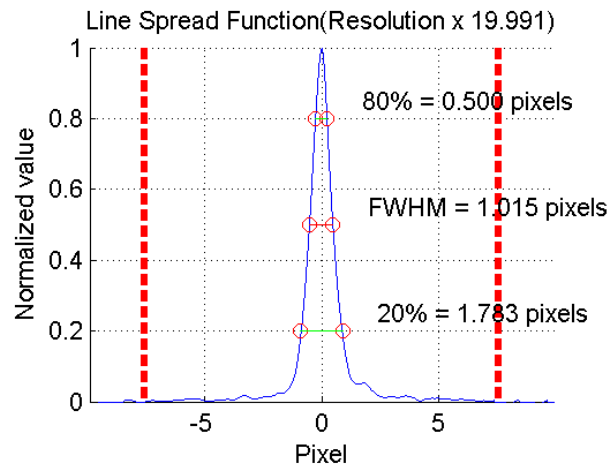
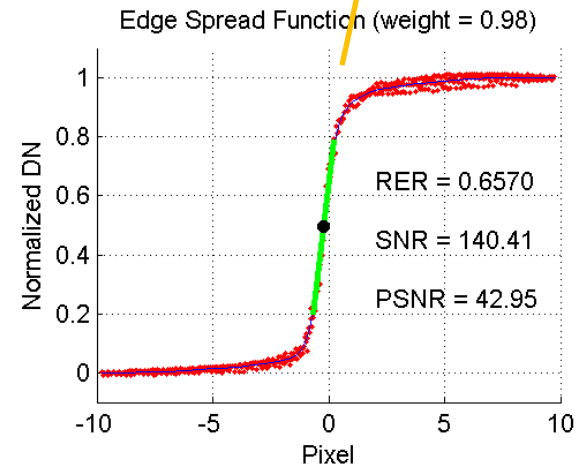
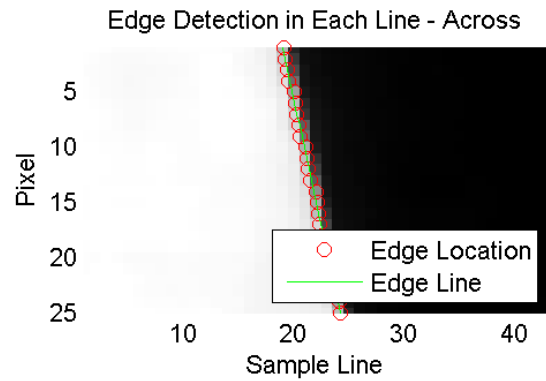
RAW image (Across)



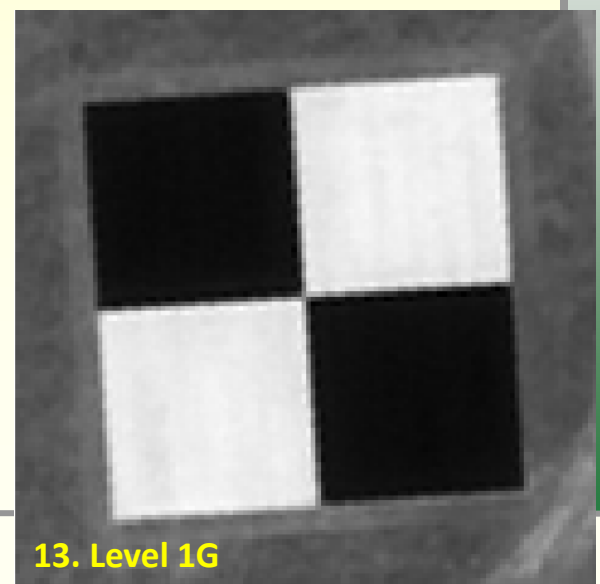
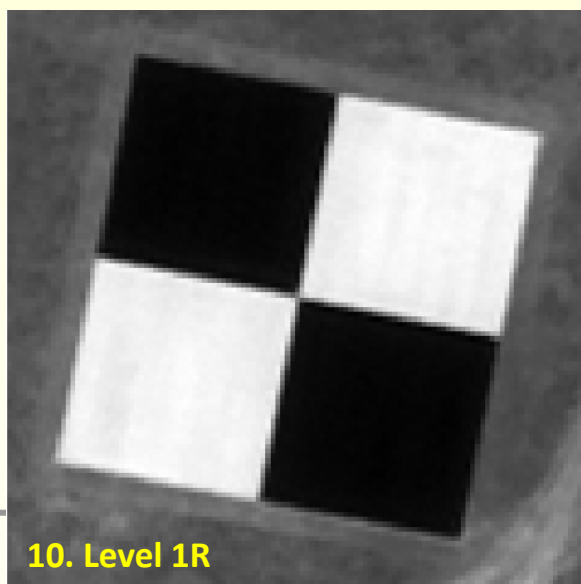
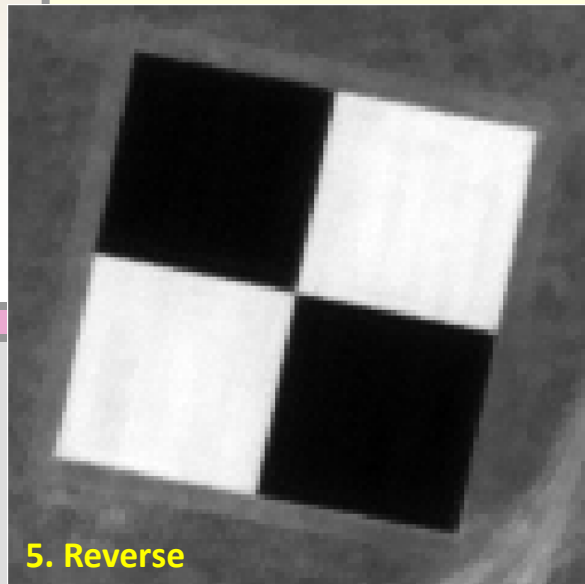
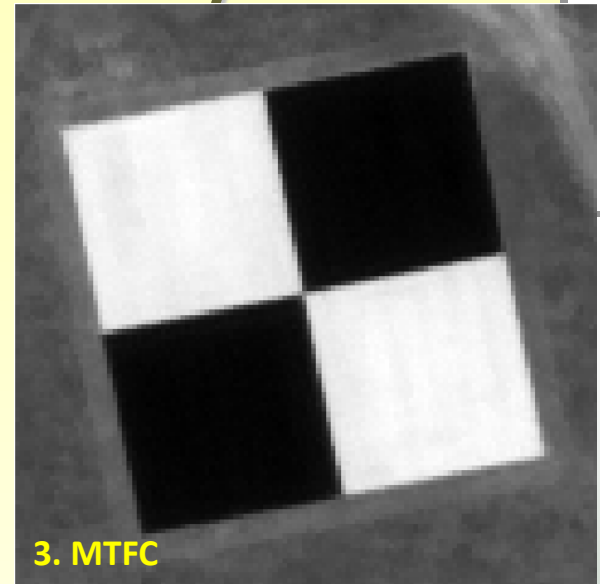
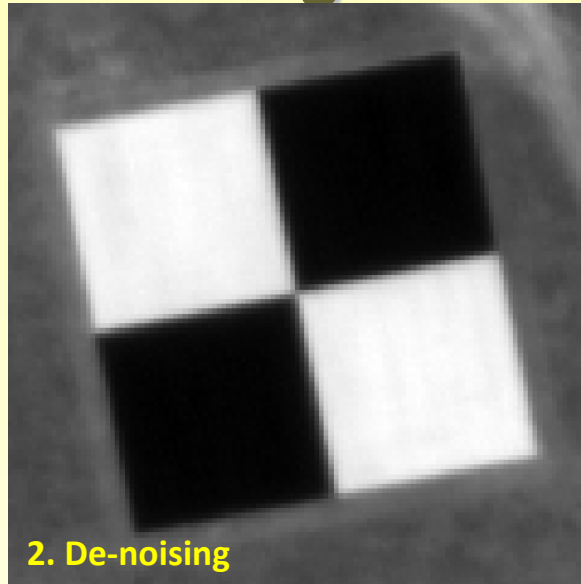
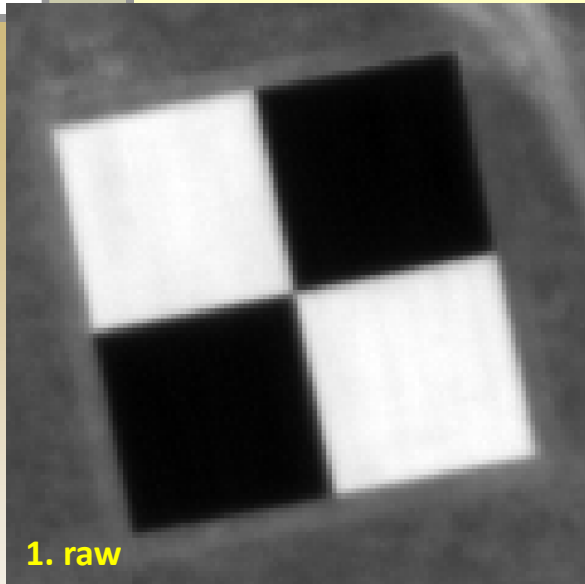
MTFC image (Across)



No Ringing~!



Product Processing Flow After Cal/Val



**Tornado, KOMPSAT-3, Louisville Mississippi USA,
imaging date: 2014.05.05**

Google Map

KOMPSAT-3



Agenda

KOMPSAT-3 Calibration and Validation

KOMPSAT-3 Image data Quality

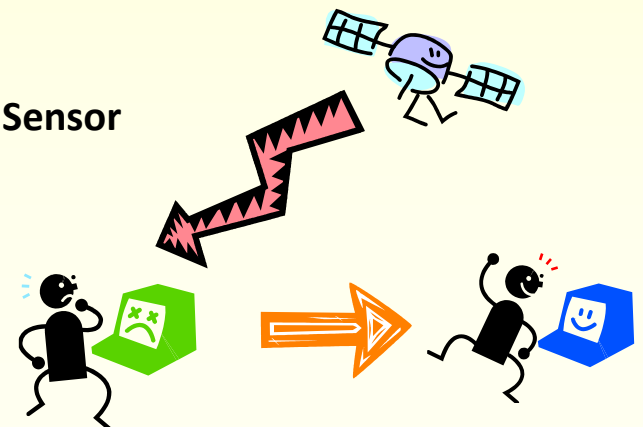
Image data Quality for User in KARI

Image data Quality for Users

- There is a **technical gap** between the **requirement for manufacturing the satellite** and the **requirement for the image data quality for Users**.
- Need & Define the **item** and the **quantitative value** for the image data quality for Users
 - Almost Users have eyes without the concept of the quantitative image data quality~!
- There are Two kind of the Quality items for Users;
 - Representative items: MTF, SNR, GSD, Absolute radiometric Gain/Offset, Radiometric resolution, etc.
 - Different valued items per each image data: Noises, etc.

With only technology of manufacturing of Satellite and Sensor, the requirements of Users cannot be complied.

- Periodical monitoring of the image data Quality
- Optimal ground processing for the Satellite and the Sensor
- Continually talking and feed back with Users



KOMPSAT-3 Product (Image data) Quality (IQ) during Normal operation

Quality Checking for K3 Product (Draft)

QR (Quality Report) for KOMPSAT-3 Image Data

❖ NO GSD, MTF, SNR on QR~!!

QR No.	QR-K3-20130314-0001														
User No.	SI														
Product ID	K3_20130310175432_04341_19891327_L1R														
S/W Version	PMS. V1.0.130306.001														
Processing Date	2013-03-06				Processed By	KARI, Gil-Dong Hong									
Anomalies Image	Band (☉- Level 2, ●- Level 3)					Constraint (TBR)			Check	Comments					
	MS				PAN	Level 1	Level 2	Level 3							
	B	G	R	N											
Dynamic range						> 1000	500-1000	< 500							
Saturation						< 1%	1-2%	> 2%							
Abnormal Pixel (except Blooming)						~2	3~10	> 10							
Equalization: inter-Detector (NUC)						20DN	20~50DN	> 50DN							
Pattern noise	diagonal, horizontal, vertical, First pixel										none	isolated noise	recurrent noise		
	Center Pattern										none	isolated noise	recurrent noise		
	Pixel burst (Port difference)										20DN	20~50DN	> 50DN		
Compression noise						none	isolated blocks	recurrent blocks							
Registration (MS-MS)						< 0.5	0.5-0.75	> 0.75							
Registration (MS-PAN)						< 0.5	0.5-0.75	> 0.75							
Location accuracy						< 70m	70-150m	> 150m							
Comments / Image chip															
Review Date					Reviewed By										
Review Comments															

Isolated & Recurrent (TBR)

	Isolated	Recurrent
Number	2~4	>= 5
Area of 1 part	100x100	100x100
DN difference	20~50 DN	> 50 DN

Level 1: Accepted

Level 2: To be Proposed

Level 3: Rejected

※ Cloud, Water, Snow area: to be take off for constraints: saturation, compression, NUC and pattern noise

(IQ) Dynamic Range

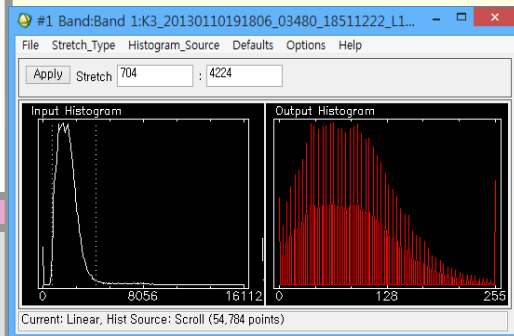
Anomalies Image	Constraint (TBR)		
	Level 1	Level 2	Level 3
Dynamic range (0 ~ 16363)	> 1000	500~1000	< 500



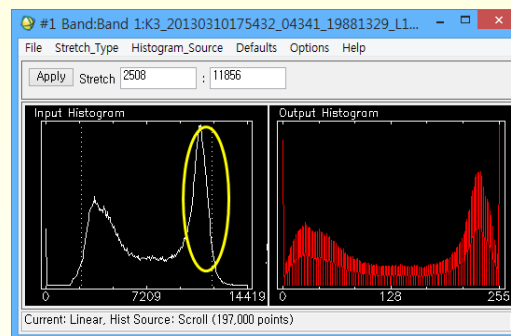
K3_20130110191806_03480_18511222_L1R



K3_20130310175432_04341_19881329_L1R



Histogram of Linear 2% in Scroll window in ENVI



- Linear 2% in Scroll window in ENVI (TBR)
 - ✓ DN(Max – Min)
 - ✓ “3500” = 4224 - 704
- Except the next area
 - ✓ Uniform bright area
 - ✓ Forest, Farm, Desert, Ice, Mountain, Big river, Big lake, etc.
 - ✓ Snow, Cloud, Ocean, etc.
- Only ROI requested by User

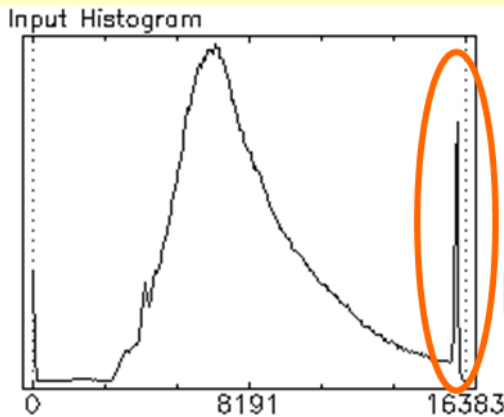
❖ User want a sufficient dynamic range in the satellite radiometric resolution.

- ✓ KOMPSAT-3: 14bit
- ✓ Not stretching in the Processing system

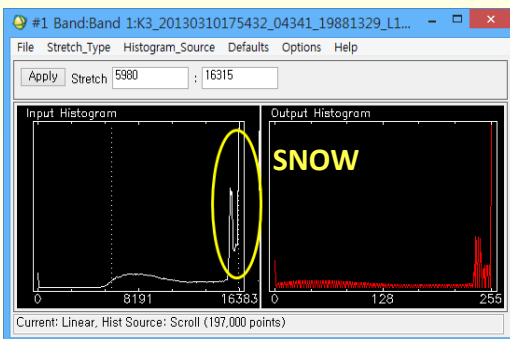
✘ For User, what is the threshold for this?

(IQ) Saturation

Anomalies Image	Constraint (TBR)		
	Level 1	Level 2	Level 3
Saturation	< 1%	1~2%	> 2%



MS Green band: Saturation in SF (2012.06.05)



K3_20130310175432_04341_19881329_L1R_B

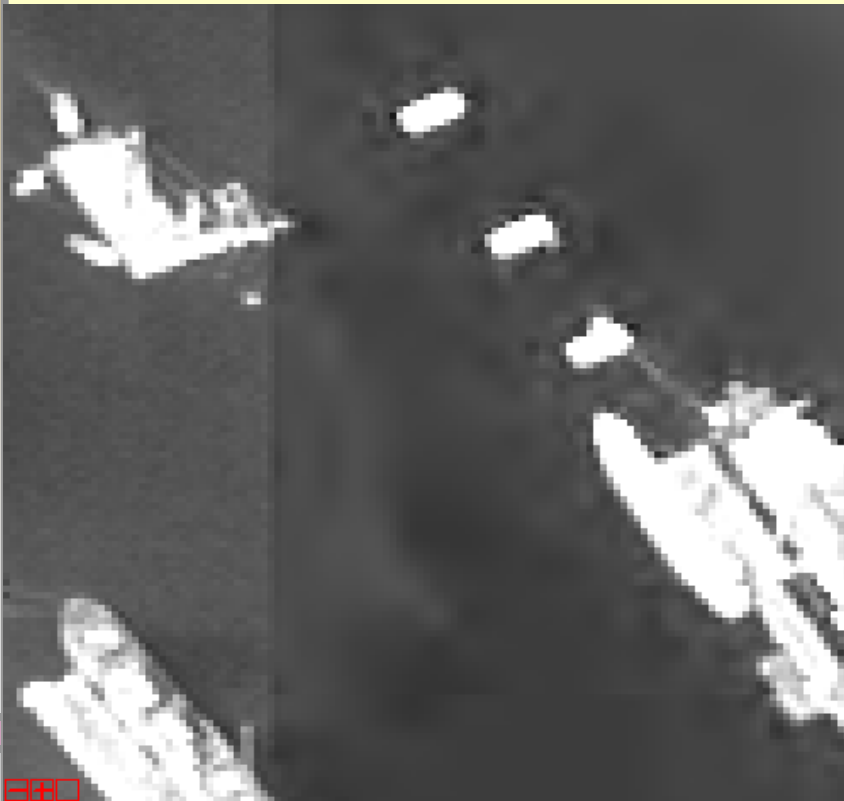
CEOS WGCV-38 (2014)

- Basically, >16383 DN, but
 - ✓ The Saturated area has a width of DN after the Processing system
- Except the next area
 - ✓ Snow, Ice, Cloud, Salt desert, etc.
- Only ROI requested by User
- ❖ User never want a saturated image data product.
 - ✓ Several exposures of Satellite be needed according to the imaging area.
 - ✓ KOMPSAT-3 has Two TDI stages.
 - ✓ KOMPSAT-3 data collection planning system has a Radiance (Reflectance) calculating module in Worldwide.

✘ For User, what is the threshold for this?

Compression noise (Additional Cal/Val item)

Anomalies Image	Constraint (TBR)			Isolated	Recurrent
	Level 1	Level 2	Level 3	Number	
Compression noise	none	isolated	recurrent	2~4	>= 5
				Area of 1 part	100x100
				DN difference	20~50 DN



- Compression ratio is '5.5' by CCSDS 122.0-B-1 (Wavelet)
 - ✓ PAN has a little
 - ✓ MS has a lot
 - ✓ Uniform area nearby high frequency area in city
- ❖ User don't want the compression noise
 - ✓ KOMPSAT-3 has been changed
 - PAN: '5.5'
 - MS: '3'
 - ✓ KOMPSAT-3 has little compression noise with the Compression ratio '3'.
- ❌ SNR on the Right side is larger than the Left.
- ❌ But, User don't want the Right side.
- ❌ For User, what is the threshold for this?

K3_20130210093832_03927_04161188_L1R_B

Issues and Discussion

Additional Cal/Val items during Normal period

- User's requirement for the Image data Quality may be different and higher than the requirements in KOMPSAT-3 system Specification.

Item	Title	Content	Status
Pixel burst	On Only MS	Develop, Test and Apply the de-noising algorithm of it	Done
Port Difference	On Only MS	Develop, Test and Apply the de-noising algorithm of it	Done
Center Pattern Difference	Different noise between each CCD Detector	After reducing Compression noise, and updating RNUC and De-noising, the Center difference has been reduced.	Done
RNUC (Residual NUC)	Non-linearity behind DN 1500	New RNUC table has been updated in the Processing system.	Done
Compression noise	Many Compression noise in MS with Compression ratio '5.5'	Updated by PAN '5.5' and MS '3'	Done

Issues and Discussion

- QR (Quality Report), that is the Internal report in KARI to monitor the KOMPSAT-3 Product (Image data) Quality, is **Draft just now**.
- Definite quantitative value for the image data Quality has to be determined.
 - ✓ For, and From User
 - ✓ Items
 - ✓ For User, what is the threshold for them?
- The main purpose of KOMPSAT-3 is just 'Detecting and Recognizing'.
 - ✓ High resolution remote sensing satellite (GSD @ nadir = 0.7m)
 - ✓ Any difference of the image data Quality according to Resolution?
 - ✓ If no, what is the **representative item of the image data Quality** for them?
- In case of KOMPSAT-3 & KOMPSAT-2,
 - ✓ After Cal/Val, all Requirements of the image data Quality were Complied.
 - ✓ But User didn't comply the Quality of K3 & K2 Product,
 - ✓ **and then, Additional Cal/Val works for User** have been done and doing~!
- We need more works for it~!

Representative & Product Quality (?)

- These are my Questions and Concerns.
- Is there standard and general Representative and Product Quality for Users?

	Car	Computer	Imagery	Remark
by Purpose	Bus, Sedan, SUV, Truck, etc.	Server, Desktop, Laptop, Tablet, etc.	SAR, IR, Visual, Resolution, etc.	
by Budget	Bentz, BMW, Lexus Toyota, Honda Hyundai, Kia	?	WV, GeoEye Pleiades, KOMPSAT SPOT, Landsat	
Representative	Model, Engine size, Transmission, etc.	CPU, Memory, HDD (SSD), Weight, OS, etc.	GSD, MTF, SNR, etc.	Performance (Specification)
Product Quality (IQ)	Scratch, Driving, etc.	Dead pixel, OS, S/W, KB, Mouse, etc.	Noise, etc.	User can look at & recognize

Importance of Quality

- There are several Use (Purpose) for Users according to the Image data Quality.
- With GSD, MTF & SNR, the Image data Quality cannot be explained more clearly to Users.
 - ✓ New representative estimator for it has to be needed.

	Car	Computer	Camera	Imagery
General Spec. (Same)	Similar Speed, 5 persons, 4 door, Extra parts	OS (Windows), Functions	No. of Pixel	GSD, Radiometric Resolution, Swath width (MTF, SNR)
Expensive (High Quality)	Comfortable, Safety, Stability, Extra function (?) Sports car	Comfortable, Fast, Clear monitor, More storage, Light (Use) Design, Develop, High technic)	DSLR, Size of CCD (CMOS) Clearness (MTF), Lens, Extra function	High Quality, Clearness, Ortho-rectified, Noise, (NIIRS) (High MTF & SNR)
Cheap (Low Quality)	Just Cheap, Mileage, Second car, First car for children	(Use) Office, Game, Internet, Education	Digital camera, Smart phone, Light, Easy, Small	Low Quality (Low MTF & SNR)

Thank you for KOMPSAT~!

