



National Remote Sensing Center of China Agency Report

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CEOS/WGCV-39 Plenary



Mission and Activities





The reports on Remote Sensing Monitoring of Global Ecosystem and Environment

The reports on Remote Sensing Monitoring of Global Ecosystem and Environment have been issued since 2012. The datasets and analytical reports are available at the Website of China Spatial Data and Information Network (<u>http://www.csi.gov.cn/index_en.html</u>).





The reports on Remote Sensing Monitoring of Global Ecosystem and Environment

Growth Conditions of Global Terrestrial Vegetation



- Global MLAI(Maximal Leaf Area Index) difference between 2012 and 2013
- Data source: MODIS reflectance product
- Spatial resolution: 1km

Aerospace Application Coordination System for Emergency Response and Data Sharing

Inter-Ministerial Coordination Mechanism **ArcSer Platform** Imagery data 65.5GB. Before disaster: 36.2GB after disaster: 29.3GB; The data was distributed to 39 disaster reduction application agencies 鲁甸县龙头山镇居民占房屋倒损遥感监测图 云南鲁甸地震重灾区山体滑坡和堰塞湖分々 1 **Disaster** Disaster **Technical** relief on support assessment site Local Institutes &

Ministries

INRSCC

Government

2014 Ludian earthquake



- KZ-1 satellite image acquisition.
- Request RESAP of ESCAP to trigger its established network for providing near-real-time satellite image.
- Acquire Indian satellite radar image before earthquake.

Organizations

Aug,4 th :	
 ArcSer platform startup, sha	aring
earthquake EO data.	5

Aerospace Application Coordination System for Emergency Response and Data Sharing





I mage of Ludian earthquakeinduced quake lake

In-situ operation based on decision supported by EO data

- Meanwhile, UAV was dispatched to a quake lake area on NiuLan River. Then the information extracted from the image was sent to the command on-site to guide quake lake's disaster rescue and relief.
- From the perspective of effectiveness on disaster reduction, UAV remote sensing system plays more and more important role in emergency response.



Aerospace Application Coordination System for Emergency Response and Data Sharing

> Apeil, 2015 Nepal earthquake



Date	25 April 2015		
Time	14:11(UTC+8)		
Magnitude	8.1 M		
Depth	20 km		
Туре	Thrust		

16:00, start KZ emergency response.

By Apr. 29, 150 scenes of KZ images were acquired.





Images of the tents which were set up at Jianggang village, China Tibet after the earthquake



Promoting EO Data Sharing

Framework of China-GEOSS Infrastructures



- Data sharing is a key component of GEOSS.
- At the 4th GEO Plenary, China and Brazil jointly announced that the China-Brazil Environment and Resources Satellite data would be shared free of charge.
- China is building a GEOSS Data Sharing Platform.
- It will also work as a portal for accessing China EO data(WIGGS task).



China GEOSS Data Sharing Platform

Capabilities of China GEOSS Data Platform

- 8 main satellite data centers integrated
- More than 30 China Coverage Datasets, 1990—now
- Metadata discoverable > 50,000,000 records
- Data accessible online > 2.5PB
- Supporting three GEO data sharing principles

High speed network connection among the centers





> EO Resources Integrated into China-GEOSS





National Integrated Earth Observation Data Sharing Platform: <u>www.chinageoss.org</u>





Regional Collaborative Mechanism on Drought Monitoring and Early Warning

China activities:



Implementation of Pilot Project on drought monitoring and early warning for Mongolia and Sri Lanka.

- Providing remote sensing data and "Drought Watching System"
- Performing in situ synchronous measurement for validation

During Oct 28-30, 2014, Training Course on Drought Monitoring organized by ESCAP and NRSCC in Beijing.





Baotou comprehensive Cal&Val site has been developed over the past several years for Cal&Val of high-resolution RS sensors.





> In last year, the site has been enhanced in many aspects:





Geometric Calibration

75 geometric control points with positional accuracy of 2cm(horizontal), 4cm (vertical).





GCP Google Earth image(from Digital Global, 0.5m)

Baotou comprehensive Cal&Val site



Microwave/optical bar-pattern target



3. The size of the gravel was calculated based on both Rayleigh roughness criterion and Oh surface radar backscatterering model, in order to exhibit sufficient contrast in Ku to S band radar image.





Microwave/optical bar-pattern target



Finished construction by the end of September, 2014



SAR corner reflector base







BIRSEL

Flight Campaigns over Baotou Cal&Val Site

2. Image quality assessment for KOMPSAT-5 SAR sensor

KOMPSAT-5 SAR image on October 22, 2014(HH Polarization)







The "image resolution" is better than 3m.

- Ground range instrument geometric resolution:1.21m
- Azimuth instrument geometric resolution: 0.90m

The resolution assessment results of the seven CRs are consist with each other except CR#7. The image of CR#7 is not a ideal point response image.







Corner reflector



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\geq 3. Image quality assessment for C-band airborne SAR



Range image resolution: 0.9m Azimuth image resolution: 1m



Corner reflector







Point target data profile

	CD No	Signal Res	olution[m]	PSLR	R [dB]	ISLR	[dB]
	CK NO.	Range	Azimuth	Range	Azimuth	Range	Azimuth
	1	0.818	0.875	-27.846	-25.483	-16.845	-12.758
	2	0.779	0.711	-24.928	-18.393	-14.921	-11.569
	3	0.773	0.815	-26.347	-22.954	-16.198	-11.851
	4	0.709	0.714	-20.049	-17.673	-14.733	-10.612
	5	0.754	0.770	-20.916	-22.712	-14.423	-11.080
	6	0.798	0.662	-24.599	-17.420	-15.809	-10.552
Observed	7	0.786	0.823	-23.888	-22.002	-14.187	-9.650
	8	0.733	0.723	-19.633	-18.416	-12.941	-9.482
	9	0.849	0.646	-21.266	-16.117	-13.386	-9.418
	10	0.742	0.702	-20.397	-18.135	-13.909	-10.121
	11	0.860	0.647	-25.628	-16.790	-12.985	-8.981
	12	0.816	0.783	-25.756	-21.243	-13.603	-8.903
	13	0.771	0.667	-22.739	-18.159	-13.472	-9.766
	14	0.699	0.814	-19.411	-21.941	-12.845	-9.289
	Mean	0.778m	0.739	-23.100	-19.817	-14.304	-10.288
Reference		0.6	0.6	< -13.26	< -13.26	< -9.8	< -9.8



4. Post-launch radiometric calibration of GF-2 satellite

Launched at Aug. 19th, 2014

Specification of GF-2/PMS			
	Pan	0.45—0.90µm	
		0.45—0.52µm	
Spectral range	Multi-spectral	0.52—0.59µm	
		0.63—0.69µm	
		0.77—0.89µm	
Resolution	Pan	1m	
	Multi-spectral	4m	
Swath	45km		
Povicit period	5d (with side-sway observation); 69d		
Revisit period	(without side-sway)		

Calibration method: On-site personnel mode









Calibration method: On-site personnel mode





Calibration method: Automated mode

Radiometric calibration system development and field campaigns





Calibration method: Automated mode

- Ground reflected spectral reflectance & radiance, atmospheric parameters were measured simultaneously;
- Both the automated and on-site personnel measured mode were tested.

Landsat 8 image (Mar. 27, 2015)



Sand field

TOA radiance comparison



	Obs.	Automat	ed mode	On-site personnel mode		
	Rau.	Sim. Rad.	RE	Sim. Rad.	RE	
Blue	81.59	73.19	10.2%	77.90	4.5%	
Green	86.11	81.74	5.0%	86.71	0.7%	
Red	92.38	89.13	3.5%	95.09	2.9%	
NIR	70.10	66.25	5.4%	70.05	0.06%	

> 5. Image quality assessment of KOMPSAT-3 and GF-2 based on the optical permanent targets.

• MTF



KOMPSAT-3 PAN image on August 14, 2014



KUMDSVT-3	AOE's	KARI's
KOIVIF SAI-S	results	results
Along track	0.083	0.091
Cross track	0.105	0.106

10	(inclusion)		
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GF-2 PAN image on Oct. 13, 2014 View zenith angle: 8.86°

	GF-2
Along track	0.0722
Cross track	0.0933

An improved "knife-edge" method is used, and has three aspects of improvements on the ISO 12233 method :

- The use of the Fermi function for edge detection.
- Filter the ESF curves using S-G filter for noise suppression.
- Process LSF curve with Hamming window for avoiding spectral leakage and making more LSF central symmetry. 2



- ➤ 5. Image quality assessment of KOMPSAT-3 and GF-2 based on the optical permanent targets.
- Spatial resolution

KOMPSAT-3 panchromatic image (2014/8/14)

GF-2 panchromatic image (2014/10/13) View zenith angle: 8.86°

SNI//			KOMPSAT-3	GF-2
		GSD	0.7m	1m
	ノ	Calculated	0 79m	1 12m
		resolution	0.7911	1.1311
		Visual	0 72m	1 05m
		resolution	0.7511	1.05111

Automated detection algorithm for calculating resolution:

- Taking the maximum radius of the target as a reference radius r_2 .
- Selecting an area containing 5 white segments .
- Detecting the number of white segment when DN differences between white and black segment <5 for a certain radius $r < r_2$, and the limited radius r_0 is acquired when number of white segment <4.
- Calculated resolution = $r_0^* \varphi$ (where φ is the angle of each segment).



Future work on Baotou Cal&Val Site



3. Offering contribution to the "global calibration" of EO through RadCalNet





Thank you for attention!