|  |  |  |
| --- | --- | --- |
|  | **Analysis Ready Data** | **Product FamilySpecification****Ocean RadarBackscatter** |

# Document Status

**For Adoption as: Product Family Specification, Ocean Radar Backscatter**

This Specification should next be reviewed on: TBD

Proposed revisions may be provided to: lsi@lists.ceos.org

# Document History

|  |  |  |  |
| --- | --- | --- | --- |
| **Version** | **Date** | **Description of Changes** | **Authors** |
| 0.01 | 28.02.2022 | Zero Draft based on the CARD4L NRB PFS v5.5 (by Rosenqvist, Albinet, Chapman, Charbonneau, Dadamia, Meyer, Miranda, Lavalle, Kellndorfer, Small, Repse, Thankappan, Tadono, Truckenbrodt, Yuan, Zhou, Zebker, Lewis, Killough, Siqueira) | Albinet, Truckenbrodt, Rosenqvist |
| 0.02 | 19.07.2022 | New items: 1.7.4, 1.7.5, 1.7.12, 2.7, 3.4, Modifications to items 2.2, 2.3, 2.4, 2.6, 3.1, 3.3, 4.2, 4.3 | Albinet, Truckenbrodt, Charbonneau, Hajduch, Rosenqvist, Small, Valentino, Tadono, Pinheiro, Zhou |
|  0.1 |  06.09.2022 |  Transcription from online draft.  Initial check. Modifications to items 1.7.4, 1.7.5, 1.7.12, 3.4 |  Rosenqvist, Charbonneau,  Albinet |
|  0.2 |  09.09.2022 |  LSI-VC-12 action: adding reference to the  land mask (items 2.2 and 1.7.13) |  Rosenqvist Albinet,  Charbonneau,  |
|  1.0 |  21.09.2022 |  Endorsement by LSI-VC |  LSI-VC-12 |

# Contributing Authors (in alphabetical order)

Clément Albinet, European Space Agency, Italy

Bruce Chapman, Jet Propulsion Laboratory, USA

François Charbonneau, Natural Resources Canada, Canada

Guillaume Hajduch, Collecte Localisation Satellites, France

Muriel Pinheiro, European Space Agency, Italy

Ake Rosenqvist, soloEO for Japan Aerospace Exploration Agency, Japan

HariPriya Sakethapuram, ISRO, India

David Small, University of Zurich, Switzerland

Takeo Tadono, Japan Aerospace Exploration Agency, Japan

John Truckenbrodt, German Aerospace Center, Germany

Antonio Valentino, RHEA for European Space Agency, Italy

Anna Wendleder, German Aerospace Center, Germany

Fang Yuan, Digital Earth Africa, Australia

Zheng-Shu Zhou, CSIRO, Australia

# Description

**Product Family Title:** **Ocean Radar Backscatter (ORB)**

**Applies to***:* Data collected by Synthetic Aperture Radar sensors.
The CEOS ARD Product Family Specifications for Synthetic Aperture Radar (SAR) data are aimed at both SAR expert users and users interested in exploring the potential of SAR but who may lack the expertise or facilities for SAR processing. The specifications are rigorously optimized to facilitate operational multi-temporal analysis with uniform data- and metadata formats that ensure multi-SAR mission interoperability. There are (as of September 2022) three CEOS ARD SAR products endorsed by CEOS LSI-VC, and two under development:

• Normalised Radar Backscatter [endorsed]

• Polarimetric Radar [endorsed]

• Ocean Radar Backscatter [endorsed]

• Geocoded Single-Look Complex [under development]

• Interferometric Products [under development]

The CEOS ARD Ocean Radar Backscatter (ORB) product specification described below has been subject to Geoid Correction and is provided in the sigma nought (s0) backscatter convention, which is recommended for most ocean applications. As the ORB product contains backscatter values only, it cannot be directly used for SAR polarimetry or interferometric applications that require local phase estimates.

It should be noted that while speckle is inherent in SAR acquisitions, unless specified in the metadata, speckle filtering has not been applied to the ORB product in order to preserve spatial resolution and user freedom. Some applications (or processing methods) may require spatial or temporal filtering for stationary backscatter estimates.

# Definitions

|  |  |
| --- | --- |
| CEOS | Committee on Earth Observation Satellites |
| ARD | Analysis Ready Data |
| ORB | Ocean Radar Backscatter |
| NRB | Normalised Radar Backscatter |
| POL | Polarimetric Radar |
| GSLC | Geocoded Single-Look Complex |
| InSAR | Interferometric Radar |
| Ancillary Data | Data other than instrument measurements, originating in the instrument itself or from the satellite, required to perform processing of the data. They include orbit data, attitude data, time information, spacecraft engineering data, calibration data, data quality information, and data from other instruments. |
| Auxiliary Data | The data required for instrument processing, which does not originate in the instrument itself or from the satellite. Some auxiliary data will be generated in the ground segment, whilst other data will be provided from external sources. |
| Metadata | Structured information that describes other information or information services. With well-defined metadata, users should be able to get basic information about data, without the need to have knowledge about its entire content. |
| Spatial Resolution | The highest magnification of the sensor at the ground surface. |
| Spatial Sampling Distance | Spatial sampling distance is the barycentre-to-barycentre distance between adjacent spatial samples on the Earth's surface. |

# Requirements

## General Metadata

*These are metadata records describing a distributed collection of pixels. The collection of pixels referred to must be contiguous in space and time. General metadata should allow the user to assess the overall suitability of the dataset, and must meet the following requirements:*

| **#** | **Item** | **Threshold (Minimum)Requirements** | **Target(Desired) Requirements** | **ThresholdSelf-Assessment** | **TargetSelf-Assessment** | **Self-Assessment Explanation/ Justification** | **Recommended Requirement Modification** |
| --- | --- | --- | --- | --- | --- | --- | --- |
| **1.1** | **Traceability** | Not required. | Data must be traceable to SI reference standard. *Note 1: Relationship to 3.4. Traceability requires an estimate of measurement uncertainty.**Note 2: Information on traceability should be available in the metadata as a single DOI landing page.* |  |  |  |  |
| **1.2** | **Metadata Machine Readability** | Metadata is provided in a structure that enables a computer algorithm to be used to consistently and automatically identify and extract each component part for further use. | As threshold, but metadata is formatted in accordance with CEOS ARD ORB Metadata Specifications, v.1.0, or a community endorsed standard that facilitates machine-readability, such as ISO 19115-2.  |  |  |  |  |
| **1.3** | **Product Type** | CEOS ARD product type name and (if required by the data provider) Copyright. | As threshold. |  |  |  |  |
| **1.4** | **Document Identifier** | Reference to CEOS ARD Ocean Radar Backscatter document as URL or DOI. | As threshold. |  |  |  |  |
| **1.5** | **Data Collection Time** | Number of source data acquisitions of the data collection is identified. The start and stop time of data collection is identified in the metadata, expressed in date/time (UTC). In case of composite products, the dates/times of the first and last data takes.  | As threshold. |  |  |  |  |
| **1.6** | **Source Data Attributes** | Sub-section describing (detailing) the SAR acquisition used to generate the CEOS ARD product.*Note: Source data attribute information are described for each acquisition and sequentially identified as acqID= 1, 2, 3, …* |  |  |  |  |
| **1.6.1** | **Source Data Access** | The metadata identifies the location from where the source data can be retrieved, expressed as a URL or DOI. | The metadata identifies an online location from where the data can be consistently and reliably retrieved by a computer algorithm without any manual intervention being required. |  |  |  |  |
| **1.6.2** | **Instrument** | The instrument used to collect the data is identified in the metadata:* Satellite name
* Instrument name
 | As threshold, but including a reference to the relevant CEOS Missions, Instruments and Measurements Database record. |  |  |  |  |
| **1.6.3** | **Source Data Acquisition****Time** | The start date and time of source data is identified in the metadata, expressed in UTC in date and time, at least to the second. | As threshold. |  |  |  |  |
| **1.6.4** | **Source Data Acquisition Parameters** | Acquisition parameters related to the SAR antenna:* Radar band
* Centre frequency Observation mode
* Polarization(s)
* Antenna pointing [Right/Left]
* Beam ID
 | As threshold. |  |  |  |  |
| **1.6.5** | **Source Data Orbit Information** | Information related to the platform orbit used for data processing: * Pass direction [asc/desc)
* Orbit data source [e.g., predicted/definite/ precise/ downlinked etc.]
 | As threshold, including also:* Platform heading angle expressed in degrees [0 360] from North
* Orbit data file containing state vectors (minimum of 5 state vectors, from 10% of scene length *before* start time to 10% of scene length *after* stop time)
* Platform (mean) altitude
 |  |  |  |  |
| **1.6.6** | **Source Data Processing Information** | Processing parameter details of the source data:* Processing facility
* Processing date
* Software version
* Product ID (file name)
* Product level
* Azimuth number of Looks
* Range number of Looks (separate values for each beam, as necessary)
 | As threshold.Plus additional relevant processing parameters, e.g., Range- and Azimuth Look Bandwidth and LUT applied. |  |  |  |  |
| **1.6.7** | **Source Data Image Attributes** | Image attributes related to the source data:* Source Data geometry (slant range/ground range)
* Azimuth pixel spacing
* Range pixel spacing
* Azimuth resolution
* Range resolution
* Near range incident angle
* Far range incident angle
 | The geometry of the image footprint expressed in WGS84 in a standardised format (e.g., WKT). |  |  |  |  |
| **1.6.8** | **Sensor Calibration** | Not required. | Sensor calibration parameters are identified in the metadata or can be accessed using details included in the metadata. Ideally this would support machine-to-machine access. |  |  |  |  |
| **1.6.9** | **Source Performance Indicators** | Provide performance indicators on data intensity noise level (NE0 and/or NE0 and/or NE0 (noise equivalent sigma and/or beta and/or gamma naught)). Provided for each polarization channel when available. Parameter may be expressed as the mean and/or minimum and maximum noise equivalent values of the source data.Values do not need to be estimated individually for each product, but may be estimated once for each acquisition mode, and annotated on all products.  | Provide additional relevant performance indicators (e.g., ENL, PSLR, ISLR etc.). |  |  |  |  |
| **1.6.10** | **Source Data Polarimetric Calibration Matrices** | Not required. | The complex-valued polarimetric distortion matrices with the channel imbalance and the cross-talk applied for the polarimetric calibration. |  |  |  |  |
| **1.6.11** | **Mean Faraday Rotation Angle** | Not required. | The mean Faraday rotation angle estimated from the polarimetric data and/or from models with reference to the method or paper used to derive the estimate.  |  |  |  |  |
| **1.6.12** | **Ionosphere Indicator** | Not required. | Flag indicating whether the backscatter imagery is “significantly impacted” by the ionosphere (0- false, 1 – true). Significant impact would imply that the ionospheric impact on the backscatter exceeds the radiometric calibration requirement or goal for the imagery. |  |  |  |  |
| **1.7** | **CEOS ARD Product Attributes** | Sub-section containing information related to the CEOS ARD ORB product generation procedure and parameters. |  |  |  |  |
| **1.7.1** | **Product Data Access** | Processing parameter details of the CEOS ARD ORB product:* Processing facility
* Processing date
* Software version
* Location from where the ORB product can be retrieved, expressed as a URL or DOI
 | The metadata identifies an online location from where the data can be consistently and reliably retrieved by a computer algorithm without any manual intervention being required. |  |  |  |  |
| **1.7.2** | **Ancillary Data** | The metadata identifies the sources of the land mask used in Item 2.2, ideally expressed as a URL or DOI. | The metadata identifies the sources of (other) ancillary data used in the generation process, ideally expressed as DOIs.*Note 1: Ancillary data includes DEMs and any additional data sources used in the generation of the product.* |  |  |  |  |
| **1.7.3** | **Product****Sample Spacing** | CEOS ARD ORB product processing parameter details:* Pixel (column) spacing
* Line (row) spacing
 | As threshold. |  |  |  |  |
| **1.7.4** | **Product Number of Looks** | Not required. | Equivalent Number of Looks (ENL)  |  |  |  |  |
| **1.7.5** | **Product Resolution** | Not required. | Average spatial resolution of the CEOS ORB product along:* Columns
* Rows
 |  |  |  |  |
| **1.7.6** | **Product****Filtering** | Flag if filter has been applied [true/false]. Metadata should include:* Reference to algorithm
* Input filtering parameters
	+ Type
	+ Window size
	+ Other filter parameters
 | As threshold. |  |  |  |  |
| **1.7.7** | **Product Bounding Box** | Two opposite corners of the product file (bounding box) are identified, expressed in the coordinate reference system defined in 1.7.11. | As threshold. |  |  |  |  |
| **1.7.8** | **Product Image Extent** | The geometry of the image footprint expressed in WGS84, in a standardised format (e.g., WKT). | As threshold. |  |  |  |  |
| **1.7.9** | **Product Image Size** | Image attributes of the CEOS ARD ORB product:* Number of lines
* Number of pixels/line
* File header size (if applicable)
* Number of no-data border pixels (if appl.)
 | As threshold. |  |  |  |  |
| **1.7.10** | **Product** **Pixel Coordinate Convention** | Coordinate referring to the Centre, or the Upper Left Corner or the Lower Left Corner of a pixel.  Values are [pixel centre, pixel ULC or pixel LLC]. | As threshold. |  |  |  |  |
| **1.7.11** | **Product Coordinate Reference System** | The metadata lists the map projection (or geographical coordinates, if applicable) that has been used and any relevant parameters required to use of data in that map projection, expressed in a standardised format (e.g., WKT). Indicate EPSG code, if defined for the CRS. | As threshold. |  |  |  |  |
| **1.7.12** | **Look Direction Polynomials** | In case the per-pixel item 2.7 (Look Direction Image) is not provided, then a list of the polynomial coefficients a­i necessary to reconstruct the look direction angle\*, together with an estimate of the accuracy, shall be provided. Example polynomial:LookDir = a­1Lat2 + a­2Lon2 + a­3LatLon + a­4Lat + a­5Lon + a­6Where:a­i = polynomial coefficientsLat = lattiude Lon = longitudeLat and Lon are the related coordinates in the product map units [‘m’, ‘deg’, ‘arcsec’]\* Note: The look direction angle represents the planar angle between north and each range direction. It is not constant in range, especially close to the poles. | As threshold. |  |  |  |  |

## Per-Pixel Metadata

*The following minimum metadata specifications apply to each pixel. Whether the metadata are provided in a single record relevant to all pixels, or separately for each pixel, is at the discretion of the data provider. Per-pixel metadata should allow users to discriminate between (choose) observations on the basis of their individual suitability for application.*

| **#** | **Item** | **Threshold (Minimum) Requirements** | **Target (Desired)Requirements** | **ThresholdSelf-Assessment** | **TargetSelf-Assessment** | **Self-Assessment Explanation/ Justification** | **Recommended Requirement Modification** |
| --- | --- | --- | --- | --- | --- | --- | --- |
| **2.1** | **MetadataMachineReadability** | Metadata is provided in a structure that enables a computer algorithm to be used to consistently and automatically identify and extract each component part for further use. | As threshold, but metadata is formatted in accordance with CEOS ARD ORB Metadata Specifications, v.1.0. |  |  |  |  |
| **2.2** | **Data MaskImage** | Mask image indicating:* Valid data
* Invalid data
* No data
* Land

File format specifications/ contents provided in metadata:* Sample Type [Mask]
* Data Format [Raw/GeoTif/COG, …]
* Data Type [Byte/Int/Float, ...]
* Bits per sample
* Byte order
* Bit value representation
 | As threshold, including e.g.,* Saturation
* Others
 |  |  |  |  |
| **2.3** | **GeoidIncidentAngleImage** | Geoid-based Local Incident angle image is provided.File format specifications/ contents provided in metadata:* Sample Type [Angle]
* Data Format
* Data Type
* Byte Order
* Bits per sample
 | As threshold. |  |  |  |  |
| **2.4** | **NoisePowerImage** | Not required. | Estimated noise equivalent σo (or 0, as applicable) used for Noise Removal, if applied, for each channel.File format specifications/ contents provided in metadata:* Sample Type [NESZ or NEBZ]
* Data Format
* Data Type
* Byte Order
* Bits per sample
 |  |  |  |  |
| **2.5** | **AcquisitionID Image** | **Note: Required for multi-source product only.** Acquisition ID, or acquisition date, for each pixel is identified. In case of multi-temporal image stacks, use source acquisition ID (i.e., 1.6 acqID values) to list contributing images.In case of Date, data represent day offset to reference observation date [UTC]. Date used as reference (“Day 0”) is provided in the metadata.Pixels not representing a unique date (e.g., pixels averaged in image overlap zones) are flagged with a pre-set pixel value that is provided in the metadata.File format specifications/ contents provided in metadata:* Sample Type [Day, ID]
* Data Format
* Data Type
* Byte Order
* Bits per sample
 | As threshold. |  |  |  |  |
| **2.6** | **Per-pixelGeoid** | Not required. | Provide Geoid as used during the geometric and radiometric processing of the SAR data, resampled to an exact geometric match in extent and resolution with the CEOS ARD ORB image product.File format specifications/ contents provided in metadata:* Sample Type [Height]
* Data Format
* Data Type
* Byte Order
* Bits per sample
* Ground Sampling Distance
 |  |  |  |  |
| **2.7** | **LookDirectionImage** | Not required. | Look Direction Image is provided. It is representing the planar angle between north and each range direction. It is not constant in range, especially near poles.File format specifications/ contents provided in metadata:* Sample Type [Height]
* Data Format
* Data Type
* Byte Order
* Bits per sample
 |  |  |  |  |

## Radiometric Corrections

*The following requirements must be met for all pixels in a collection. The requirements indicate the necessary outcomes and to some degree the minimum steps*

*necessary to be deemed to have achieved those outcomes.*

| **#** | **Item** | **Threshold (Minimum)Requirements** | **Target (Desired)Requirements** | **ThresholdSelf-Assessment** | **TargetSelf-Assessment** | **Self-Assessment Explanation/ Justification** | **Recommended Requirement Modification** |
| --- | --- | --- | --- | --- | --- | --- | --- |
| **3.1** | **Backscatter Measurements** | Geoid-corrected Sigma-Nought backscatter coefficient (s0) is provided for each available polarization.File format specifications/contents provided in metadata:* Measurement Type [Sigma-Nought]
* Backscatter Expression Convention [linear amplitude or linear intensity\*]
* Backscatter Conversion Equation
* Polarization [HH/HV/VV/VH]
* Data Format [GeoTif/COG, …]
* Data Type [Byte/Int/Float, ...]
* Byte order
* Bits per sample

*\* Note: transformation to the logarithm decibel scale is not required or* desired *as this step can be easily completed by the user if necessary.* | As threshold. |  |  |  |  |
| **3.2** | **Noise Removal** | Flag if noise removal\* has been applied (Y/N). Metadata should include reference to algorithm as URL or DOI.\* *Note: Thermal noise removal and image border noise removal to remove overall scene noise and scene edge artefacts, respectively.* | As threshold. |  |  |  |  |
| **3.3** | **Radiometric Accuracy** | Not required. | Uncertainty (e.g., bounds on s0) information is provided as document referenced as URL or DOI. SI traceability is achieved. |  |  |  |  |
| **3.4** | **Mean Wind- Normalised Backscatter Measurements** | Not required. | Mean wind-normalised (over ocean) backscatter coefficient is provided for each available polarization. It is calculated as the ratio between the backscatter intensity and a simulated backscatter intensity image generated using an ocean surface wind model.File format specifications/contents provided in metadata:* Measurement Type [Wind-Normalised Backscatter]
* Backscatter Expression Convention [intensity ratio]
* Polarization [HH/HV/VV/VH]
* Data Format [GeoTif/COG, …]
* Data Type [Byte/Int/Float, ...]
* Byte order
* Bits per sample

*Note 1: Reference wind model, wind speed and direction used for reference backscattering coefficient should be provided.* |  |  |  |  |

## Geometric Corrections

*Geometric corrections must place the measurement accurately on the surface of the ocean (that is, geolocate the measurement) allowing measurements taken*

*through time to be compared.*

| **#** | **Item** | **Threshold (Minimum)Requirements** | **Target(Desired) Requirements** | **ThresholdSelf-Assessment** | **TargetSelf-Assessment** | **Self-Assessment Explanation/ Justification** | **Recommended Requirement Modification** |
| --- | --- | --- | --- | --- | --- | --- | --- |
| **4.1** | **GeometricCorrectionAlgorithms** | Not required. | Metadata references:* A metadata citable peer-reviewed algorithm
* Technical documentation regarding the implementation of that algorithm expressed as URLs or DOIs
* The sources of ancillary data used to make corrections
* Resampling method used for geometric processing of the source data

*Note 1: Examples of technical**documentation can include e.g., an Algorithm, Theoretical Basis Document, a Product User Guide.* |  |  |  |  |
| **4.2** | **Geoid** | 1. During ortho-rectification, the data provider shall use the same Geoid that was used for the radiometric geoid flattening to ensure consistency of the data stack.
2. Provide reference to the Geoid used for the radiometric geoid flattening.
3. Provide reference to Earth Gravitational Model (EGM) used for Geometric Correction.
 | As threshold. |  |  |  |  |
| **4.3** | **GeometricAccuracy** | An estimate of the absolute localisation error is provided as bias and standard deviation, provided in slant range/azimuth, or Northing/Easting. *Note 1: Can be obtained from corner reflector measurements or mission calibration/ validation results.* *Note 2: Accurate geolocation is a prerequisite to enable time-series analysis or interoperability between radar sensors.* | Output product sub-sample accuracy should be less than or equal to 3-pixel radial root mean square error (rRMSE).Provide documentation of estimate of absolute localisation error as DOI or URL. |  |  |  |  |
| **4.4** | **Gridding Convention**  | A consistent gridding/sampling frame is used. The origin is chosen to minimise any need for subsequent resampling between multiple products (be they from the same or different providers). This is typically accomplished via a “snap to grid” in relation to the most proximate grid tile in a global system.\*\*\*\* If a product hierarchy of resolutions exists (or is planned), the multiple resolutions should nest within each other (e.g., 12.5 m, 25 m, 50 m, 100 m, etc.), and not be disjoint.  | Provide DOI or URL to gridding convention used.When multiple providers share a common map projection, providers are encouraged to standardise the origins of their products among each other.In the case of UTM/UPS coordinates, the upper left corner coordinates should be set to an integer multiple of sample intervals from a 100 km by 100 km grid tile of the Military Grid Reference System's 100k coordinates (“snap to grid”). For products presented in geographic coordinates (latitude and longitude), the origin should be set to an integer multiple of samples in relation to the closest integer degree. |  |  |  |  |

# Summary Self-Assessment Table

|  |  | **Threshold** | **Target** |
| --- | --- | --- | --- |
| **1** | **General Metadata** |  |  |
| 1.1 | Traceability |  |  |
| 1.2 | Metadata Machine Readability |  |  |
| 1.3 | Product Type |  |  |
| 1.4 | Document Identifier |  |  |
| 1.5 | Data Collection Time |  |  |
| **1.6** | **Source Data Attributes** |  |  |
| 1.6.1 | Source Data Access |  |  |
| 1.6.2 | Instrument |  |  |
| 1.6.3 | Source Data Acquisition Time |  |  |
| 1.6.4 | Source Data Acquisition Parameters |  |  |
| 1.6.5 | Source Data Orbit Information |  |  |
| 1.6.6 | Source Data Processing Information |  |  |
| 1.6.7 | Source Data Image Attributes |  |  |
| 1.6.8 | Sensor Calibration |  |  |
| 1.6.9 | Source Performance Indicators |  |  |
| 1.6.10 | Source Data Polarimetric Calibration Matrices |  |  |
| 1.6.11 | Mean Faraday Rotation Angle |  |  |
| 1.6.12 | Ionosphere Indicator |  |  |
| **1.7** | **CEOS ARD Product Attributes** |  |  |
| 1.7.1 | Product Data Access |  |  |
| 1.7.2 | Ancillary Data |  |  |
| 1.7.3 | Product Sample Spacing |  |  |
| 1.7.4 | Product Number of Looks |  |  |
| 1.7.5 | Product Resolution |  |  |
| 1.7.6 | Product Filtering |  |  |
| 1.7.7 | Product Bounding Box |  |  |
| 1.7.8 | Product Image Extent |  |  |
| 1.7.9 | Product Image Size |  |  |
| 1.7.10 | Product Pixel Coordinate Convention |  |  |
| 1.7.11 | Product Coordinate Reference System |  |  |
| 1.7.12 | Look Direction Polynomials |  |  |
| **2** | **Per-Pixel Metadata** |  |  |
| 2.1 | Metadata Machine Readability |  |  |
| 2.2 | Data Mask Image |  |  |
| 2.3 | Geoid Incident Angle Image |  |  |
| 2.4 | Noise Power Image |  |  |
| 2.5 | Acquisition ID Image |  |  |
| 2.6 | Per-Pixel Geoid |  |  |
| 2.7 | Look Direction Image |  |  |
| **3** | **Radiometric Corrections** |  |  |
| 3.1 | Backscatter Measurements |  |  |
| 3.2 | Noise Removal |  |  |
| 3.3 | Radiometric Accuracy |  |  |
| 3.4 | Mean Wind-Normalised Backscatter Measurements |  |  |
| **4** | **Geometric Corrections** |  |  |
| 4.1 | Geometric Correction Algorithms |  |  |
| 4.2 | Geoid |  |  |
| 4.3 | Geometric Accuracy |  |  |
| 4.4 | Gridding Convention |  |  |

# Guidance

This section aims to provide background and specific information on the processing steps that can be used to achieve analysis ready data. This Guidance material does not replace or override the specifications.

# Introduction to CEOS ARD

**What are CEOS Analysis Ready Data (CEOS ARD) products?**

CEOS ARD products have been processed to a minimum set of requirements and organized into a form that allows immediate analysis with a minimum of additional user effort. These products would be resampled onto a common geometric grid (for a given product) and would provide baseline data for further interoperability both through time and with other datasets.

CEOS ARD products are intended to be flexible and accessible products suitable for a wide range of users for a wide variety of applications, including particularly time series analysis and multi-sensor application development. They are also intended to support rapid ingestion and exploitation via high-performance computing, cloud computing, and other future data architectures. They may not be suitable for all purposes and are not intended as a ‘replacement’ for other types of satellite products.

**When can a product be called CEOS ARD?**

The CEOS ARD branding is applied to a particular product once:

* the product has been assessed as meeting CEOS ARD requirements by the agency responsible for production and distribution of the product, and
* the assessment has been peer reviewed by the CEOS Land Surface Imaging Virtual Constellation in consultation with the CEOS Working Group on Calibration and Validation.

Agencies or other entities considering undertaking an assessment process should contact the co-leads of the [Land Surface Imaging Virtual Constellation](http://ceos.org/ourwork/virtual-constellations/lsi/).

A product can continue to use CEOS ARD branding as long as its generation and distribution remain consistent with the peer-reviewed assessment.

**What is the difference between Threshold and Target?**

Products that meet all threshold requirements should be immediately useful for scientific analysis or decision-making.

Products that meet target requirements will reduce the overall product uncertainties and enhance broad-scale applications. For example, the products may enhance interoperability or provide increased accuracy through additional corrections that are not reasonable at the *threshold* level.

Target requirements anticipate continuous improvement of methods and evolution of community expectations, which are both normal and inevitable in a developing field. Over time, *target* specifications may (as subject to due process) become accepted as *threshold* requirements.