

## Copernicus Sentinel-4/UVN pre-launch plans

### Berit Ahlers and S4/UVN team

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- 1. Sentinel-4/ UVN apportionment
  - instrument design calibration LOL1b processing
- 2. LO performance verification and calibration
  - example radiometric calibration
- 3. contamination prevention (optical degradation)



# S4/UVN specifications apportionment



maintain **overview** and sensible Instrument design apportionment at system level **Opto-mechanical** space segment compliance with Thermal instrument level 1b **Electrical** requirements at I/F BOL and EOL Data processing  $\bigotimes$ LO to L1b Calibration L0/L1b(overall including in flight) **ATBD** L1b optimisation **On-ground** considering instrument performance at L1b, accuracy budgets and programmatic aspects

# S4/UVN on-ground and in-flight requirements





esa

## S4/UVN instrument

ZUVN





## S4/UVN calibration sources







**Objective:** to verify is S4/UVN instrument is built as designed @Level 0 under flight representative environmental conditions **'Test as you fly'** incl.:

- verification instrument sufficiently insensitive to incident polarisation
- 2. no **spectral features** in instrument response interfering with atmospheric gas absorptions
- 3. straylight



### **S4/UVN** spectral features



#### DOAS analysis of satellite spectra



Note how small the

NO<sub>2</sub> features are, about 0.5% signal strength of the total signal

Contributors to these spectral features are: polarisation scrambler, coatings, gratings, sun diffuser, straylight, gain change, ...







**Objective:** to retrieve calibration key parameters.

**1. radiometric calibration** Earth spectral radiance, solar spectral irradiance and derived Earth reflectance (radiance/irradiance)

### 2. spectral calibration

- a. wavelength scale for uniform and non-uniform ground scenes
- b. Instrument Spectral Response Function (ISRF)
- c. optical bench temperature (gradient) dependencies
- 3. spectral/ spatial straylight
- 4. electronic and detector calibration parameters
- **5. geometric** parameters, co-registration, Image Navigation and Registration (INR), geolocation



## Flow down to component level



### 1. component

e.g. characterisation of diffuser, scan mirror (transmission, angle dependence, radiation, ...)

### 2. sub-system

e.g. Focal Plane Assembly sub-system (detector, FEE/FSE, FPA housing)

### 3. system

S4/UVN instrument models

AND calibration **facility**, optical, mechanical, electrical ground support equipment (**GSE's**)



## RAL Space/UK new building status 17 Feb 2015







## RAL Space UK



door port machining (9thApril)

Sentinel 4/UVN instrument in STC-5m using AIRBUS CAD models

© 2015 RAL Space/ Airbus



# S4/UVN absolute radiometric accuracy

![](_page_12_Picture_1.jpeg)

**3%** (threshold), **2%** (goal), accounting for all error contributions (straylight, polarisation, smear,...) at level 1b (after corrections) Calls for building-up an error budget accounting for contributions from:

• instrument design

ernicus

- instrument on-ground and in-flight calibration
- signal processing L0 to L1b

Similar requirements exist for **on-ground** measurements\*

- instrument response in Sun calibration mode shall be calibrated better than 0.8%
- instrument response in Earth observation mode shall be calibrated better than 1.0%
- instrument response in Earth reflectance shall be calibrated better than 1.0%

### **Radiometric calibration parameters**

![](_page_13_Picture_1.jpeg)

- 1. absolute Earth spectral radiance
- 2. absolute Sun spectral irradiance
- 3. Earth viewing angle dependency

(North-South on detectors and scan mirror)

- 4. Sun viewing angle dependency
- 5. absolute **Earth reflectance**: Earth radiance/ solar irradiance, using dedicated sources optimised for this parameter

In orbit, relative radiometric **degradation** monitored and quantified primarily with **Sun irradiance** measurements, but also with **WLS** and **LED**, **Earth radiance** and **moon** measurements.

![](_page_13_Picture_9.jpeg)

## Absolute radiometric radiance calibration esa

using calibrated sources (FEL lamp, integrating sphere) and radiance angle dependency calibration measurements under flight-representative thermal-vacuum conditions

![](_page_14_Figure_2.jpeg)

### Absolute radiometric radiance calibration CSA - on ground

using calibrated source cross calibration with respect to FEL lamp

![](_page_15_Figure_2.jpeg)

![](_page_15_Picture_3.jpeg)

### **Radiometric measurements**

![](_page_16_Picture_1.jpeg)

Using <b>different radiometric sources</b> is <b>absolutely</b> <b>essential</b> to obtain required radiometric accuracy and to quantify measurement uncertainties. Measurement sequence include: • absolute radiance/ irradiance/ reflectance				OGSE	Radiance	Irradiance
			1	FEL	1R	11
			2	SBS	2R	21
<ul><li>irradiance goniometry</li><li>radiance angular dependency</li></ul>			3	Integr. Sphere	3R	31
Product	Msm	Comment				
Refl	21/2R	Best (calibration keydata)				
Refl_FEL	1I/1R	Analysis result from measurement expected to be less good				
Abs_Rad	1R	Calibration keydata (expected to be the most accurate key parameter to be used for L0 to L1b processing)				
Abs_Irrad	Abs_Rad x Refl	Best (expected to be the most accurate key parameter to be used for L0 to L1b processing)				
Abs_Irrad_FEL	11	Analysis result from measurement expected to be less good				
Ang_dept _sphere	3R	Radiance angular dependence				
Refl_sphere	31/3R	Instrument BSDF				
Abs_Rad 2	3R	Radiance angular dependency & calibration keydata				

Refl_sphere	31/3R	Instrument BSDF
Abs_Rad <sup>2</sup>	3R	Radiance angular dependency & calibration keydata (to be used in L0 to 1 processing in case more accurate than Abs_Rad)
Abs_Irrad'	Abs_Rad' x Refl	Calibration keydata (to be used in L0 to 1 processing in case more accurate than Abs Irrad)

## Solar occultation/ zenith sky

![](_page_17_Picture_1.jpeg)

(dark lines in bright scene instead of bright lines from OGSE with dark background)

real atmospheric radiance source as stimulus

#### end-to-end performance

Close loop between atmospheric measurements, processing calibration and instrument hardware up to level 2

![](_page_17_Picture_6.jpeg)

![](_page_17_Picture_7.jpeg)

## Decontamination measures to prevent optical degradation (examples)

![](_page_18_Picture_1.jpeg)

- **bake-out** after launch (additional heater power)
- protection optical components from e.g. solar flux
- warm-up possibilities independently for detectors/optical bench
- protection solar diffusers
  - no measurements several weeks after launch
  - no measurements after yaw flip
  - no measurements after thrusters' usage
- purging
- avoidance humidity
- avoid materials degrading under space environment (e.g. relevant light fluxes, atomic oxygen, radiation, TV, molecular contamination)

![](_page_18_Picture_12.jpeg)

![](_page_19_Picture_1.jpeg)

S4/UVN instrument design, LO performance verification and calibration (on ground 'Test as you fly' and in flight).

Attention for **balance** between L0 **performance**, **calibration** and level 0 to 1b **data processing** to deliver L1b data products within the required specification at End of Life.

S4/UVN instrument well equipped with **on-board calibration hardware**.

Phase C/D ongoing.

![](_page_19_Picture_6.jpeg)

## Thank you for your attention!

![](_page_20_Picture_1.jpeg)

For further information:

#### ESA Copernicus website http://www.esa.int/copernicus

EC Copernicus website http://www.copernicus.eu/